Scalability of Parallel Programs

How is my parallel code performing?
Outline

• Scalability

• Amdahl’s law

• Gustafson’s law

• Load balance
Performance metrics

- Measure the execution time $T$
  - how do we quantify performance improvements?

- Speed up
  - typically $S(N,P) < P$

- Parallel efficiency
  - typically $E(N,P) < 1$

- Serial efficiency
  - typically $E(N) \leq 1$

$$S(N, P) = \frac{T(N,1)}{T(N,P)}$$

$$E(N, P) = \frac{S(N,P)}{P} = \frac{T(N,1)}{PT(N,P)}$$

$$E(N) = \frac{T_{best}(N)}{T(N,1)}$$

Where $N$ is the size of the problem and $P$ the number of processors.
Scaling

*Scaling* is how the performance of a parallel application changes as the number of processors is increased.

There are two different types of scaling:

- **Strong Scaling** – total problem size stays the same as the number of processors increases.
- **Weak Scaling** – the problem size increases at the same rate as the number of processors, keeping the amount of work per processor the same.

Strong scaling is generally more useful and more difficult to achieve than weak scaling.
Strong scaling

![Graph showing speed-up vs number of processors. The graph has two lines: one linear and one actual. The x-axis represents the number of processors, and the y-axis represents speed-up. The linear line grows linearly with the number of processors, while the actual line shows a slight deviation from linearity. The graph is labeled with 'Speed-up vs No of processors.'
Weak scaling

- **Runtime (s)** vs. **No. of processors**

  - **Actual** line
  - **Ideal** line

  - **Archer** and **EPCC** logos
The serial section of code

“The performance improvement to be gained by parallelisation is limited by the proportion of the code which is serial”

Gene Amdahl, 1967
Amdahl’s law

• A typical program has two categories of components
  • Inherently sequential sections: can’t be run in parallel
  • Potentially parallel sections
• A fraction, $\alpha$, is completely serial

• Parallel runtime
  • Assuming parallel part is 100% efficient

\[ T(N, P) = \alpha T(N, 1) + \frac{(1-\alpha)T(N,1)}{P} \]

• Parallel speedup

\[ S(N, P) = \frac{T(N, 1)}{T(N, P)} = \frac{P}{\alpha P + (1 - \alpha)} \]

• We are fundamentally limited by the serial fraction
  • For $\alpha = 0$, $S = P$ as expected (i.e. efficiency = 100%)
  • Otherwise, speedup limited by $1/\alpha$ for any $P$
    • For $\alpha = 0.1$; $1/0.1 = 10$ therefore 10 times maximum speed up
    • For $\alpha = 0.1$; $S(N, 16) = 6.4$, $S(N, 1024) = 9.9$
Gustafson’s Law

- We need larger problems for larger numbers of CPUs

- Whilst we are still limited by the serial fraction, it becomes less important
Utilising Large Parallel Machines

• Assume parallel part is proportional to $N$
  • serial part is independent of $N$

  \[ T(N, P) = T_{\text{serial}}(N, P) + T_{\text{parallel}}(N, P) \]
  \[ = \alpha T(1, 1) + \frac{(1-\alpha)NT(1,1)}{P} \]

• speedup
  \[ S(N, P) = \frac{T(N,1)}{T(N,P)} = \frac{\alpha+(1-\alpha)N}{\alpha+(1-\alpha)\frac{N}{P}} \]

• Scale problem size with CPUs, i.e. set $N = P$ (weak scaling)
  • speedup
    \[ S(P, P) = \alpha + (1 - \alpha)P \]
  • efficiency
    \[ E(P, P) = \frac{\alpha}{P} + (1 - \alpha) \]
Gustafson’s Law

• If you can increase the amount of work done by each process/task then the serial component will not dominate
  • Increase the problem size to maintain scaling
  • This can be in terms of adding extra complexity or increasing the overall problem size.

• \[ S(\text{N} \times \text{P}, \text{P}) = P - \alpha (P - 1) \]

• For instance, \( \alpha = 0.1 \)
  • \( S(16 \times \text{N}, 16) = 14.5 \)
  • \( S(1024 \times \text{N}, 1024) = 921.7 \)

Due to the scaling of \( N \), effectively the serial fraction becomes \( \alpha / P \)
Analogy: Flying London to New York
Buckingham Palace to Empire State

• By Jumbo Jet
  - distance: 5600 km; speed: 700 kph
  - time: 8 hours?

• No!
  - 1 hour by tube to Heathrow + 1 hour for check in etc.
  - 1 hour immigration + 1 hour taxi downtown
  - fixed overhead of 4 hours; total journey time: 4 + 8 = 12 hours

• Triple the flight speed with Concorde to 2100 kph
  - total journey time = 4 hours + 2 hours 40 mins = 6.7 hours
  - speedup of 1.8 not 3.0

• Amdahl’s law!
  \[ \alpha = \frac{4}{12} = 0.33; \text{ max speedup } = 3 \text{ (i.e. 4 hours)} \]
Buckingham Palace to Sydney Opera

• By Jumbo Jet
  • distance: 16800 km; speed: 700 kph; flight time: 24 hours
  • serial overhead stays the same: total time: 4 + 24 = 28 hours

• Triple the flight speed
  • total time = 4 hours + 8 hours = 12 hours
  • speedup = 2.3 (as opposed to 1.8 for New York)

• Gustafson’s law!
  • bigger problems scale better
  • increase both distance (i.e. \( N \)) and max speed (i.e. \( P \)) by three
  • maintain same balance: 4 “serial” + 8 “parallel”
Load Imbalance

• These laws all assumed all processors equally busy
  • what happens if some run out of work?

• Specific case
  • four people pack boxes with cans of soup: 1 minute per box

<table>
<thead>
<tr>
<th>Person</th>
<th>Anna</th>
<th>Paul</th>
<th>David</th>
<th>Helen</th>
<th>Total</th>
</tr>
</thead>
<tbody>
<tr>
<td># boxes</td>
<td>6</td>
<td>1</td>
<td>3</td>
<td>2</td>
<td>12</td>
</tr>
</tbody>
</table>

• takes 6 minutes as everyone is waiting for Anna to finish!
• if we gave everyone same number of boxes, would take 3 minutes

• Scalability isn’t everything
  • make the best use of the processors at hand before increasing the number of processors
Quantifying Load Imbalance

- Define Load Imbalance Factor

\[ LIF = \frac{\text{maximum load}}{\text{average load}} \]

- for perfectly balanced problems: \( LIF = 1.0 \)
- in general, \( LIF > 1.0 \)
- \( LIF \) tells you how much faster calculation could be with balanced load

- Box packing
  - \( LIF = 6/3 = 2 \)
  - initial time = 6 minutes; best time = \( 6/LIF = 3 \) minutes
Summary

• Scaling is important, as the more a code scales the larger a machine it can take advantage of
  • can consider weak and strong scaling
  • in practice, overheads limit the scalability of real parallel programs
  • Amdahl’s law models these in terms of serial and parallel fractions
  • larger problems generally scale better: Gustafson’s law

• Load balance is also a crucial factor

• Metrics exist to give you an indication of how well your code performs and scales