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Exercise: Parallel Traffic Modelling

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1 Introduction and Aims

The aim of this exercise is to take a simple example, the 1D traffic model as described in the lectures, and parallelise it in various ways. Although this code is probably not sufficiently complicated to show substantial performance differencess, the idea is for you to experiment with different techniques in the simple traffic model before implementing them in a real MPI application.

You will be given source code, implemented in both C and Fortran, that contains:

1. a working serial code;
2. a working MPI code;
3. Makefiles and template batch submission scripts for ARCHER.

The exercises below range from fairly basic to very advanced. Please start at whatever level you want to!

2 Instructions

Obtain the code as `traffic-mpiscale.tar` from the course web page.

2.1 Verification

The way it is written the code should give **exactly** the same answer for both languages regardless of whether it is serial or parallel. For a road of length 100000, the velocity at iteration 2000 should be 0.931989 (to 6 decimal places). If you get a different answer then your code is probably wrong!

You can experiment with increasing the length of the road – just change the value of `ncell` near the top of the main program. If you decide to use a road of a different length, you should re-run the serial code to get a new baseline result. Note that the way the MPI code is implemented, it assumes that the **length of the road** is an **exact multiple** of the number of processes.

The number of iterations is set quite low and you may wish to increase this when measuring performance so that the parallel code still runs for a reasonable length of time (e.g. for around a second). Simply multiply the value of maxiter by, say, a factor of 10:

```
maxiter = 200000000/ncell;
maxiter = maxiter*10;
printfreq = maxiter/10;
...
```

3 MPI exercises

These range from fairly basic to very advanced. Please attempt whatever ones you feel comfortable with.

1. Run the MPI code on a range of process counts (e.g. 1, 2, 5, 10, 20, 40 and 50) and plot a graph of the speedup against the number of processes.
2. Do the same with very short and very long roads and compare the performance results.
3. The global sum requires a parallel reduction `MPI_Allreduce` which is an expensive operation. Modify the code so it only calls reductions when necessary; investigate the effect on performance.
4. Replace the `MPI_Sendrecv` call with separate calls to `MPI_Send` and `MPI_Recv` and check that the code still runs correctly. Note that you have probably written a technically incorrect code because `MPI_Send` could be implemented as a synchronous send.
5. Replace the call to `MPI_Send` with `MPI_Ssend` to guarantee that it is implemented synchronously. As it stands, your code will probably deadlock (see Section 3.1 for more exercises on this topic).
6. Fix the deadlock by arranging the processes into odd/even pairs where, in each pair, one process sends first then receives and the other receives first then sends.
7. Solve the deadlock problem using non-blocking operations. There are a number of options:

   (a) a non-blocking send (`MPI_ISsend`), a blocking receive (`MPI_Recv`) and a wait (`MPI_Wait`);

   (b) a non-blocking receive, a blocking send and a wait;

   (c) a non-blocking send, a non-blocking receive and multiple waits (e.g. `MPI_Waitall`).

   When developing the non-blocking code, you should use synchronous send (i.e `MPI_Ssend` / `MPI_Issend`) as opposed to standard send (`MPI_Send`). This ensures an incorrect code is guaranteed to deadlock; with standard sends, an incorrect code might just happen to run correctly which is not desirable. Once working you can switch to `MPI_Isend` which should improve performance.
8. Put an `MPI_Barrier` at the end of every iteration. Although this is **completely unnecessary**, many people do this kind of thing "just to be safe". What is the effect on performance?
9. Implement the non-blocking halo exchange using *persistent communications*. In the case of running on 2 processes, where the up and down neighbour are both the same process, can you guarantee that the sends and receives will match correctly?
10. Try to overlap some of the computation with communications, i.e. update the interior cells of the road while waiting for the halo data to arrive.
11. Minimise the latency overhead by using deep halos, i.e. exchange more than one boundary element and then do multiple iterations before the next halo swap. It is much easier to implement an explicit depth first (e.g. 2 halo points) before attempting the general case of depth D.
12. Combine deep halos with overlapping communication and calculation.

3.1 Non-periodic boundary conditions

The reason that the traffic model deadlocks with a naive implementation using synchronous sends is because of the periodic boundary conditions: all processes are trying to send at the same time. With non-periodic boundaries, however, processes at the extreme ends of the road will not need to send or receive some of the data and the deadlock is broken.

Update the traffic model to use non-periodic boundaries:

1. Set the halo at the exit of the road (on the last process) to be zero so cars are always free to leave;
2. Each iteration, set the halo data at the entrance to the road (on the first process) to be 1 with probability `density`, otherwise set to zero. This maintains the same density of traffic for the whole simulation; see `initroad()` to see how to call the random number generator.
3. Run the code on one and many processes; does it give the same answer? Do you understand why?
4. Implement the halo swapping using blocking synchronous sends and receives (`MPI_Ssend` / `MPI_Recv`); unlike the periodic case, the code **should not** deadlock.
5. Compare the performance with the version using `MPI_Sendrecv` and using `MPI_Send` / `MPI_Recv`. Although it works correctly, the synchronous version should be slower; do you understand why?

4 OpenMP exercises

1. Run the OpenMP code on a range of thread counts (e.g. 1, 2, 5, 10, 20 and 28) and plot a graph of the speedup against the number of threads.
2. Change the code so it only computes the total number of moves when absolutely necessary. How does the impact on performance compare with the equivalent optimisation in MPI?
3. Before the first call to `initroad()`, zero both the `oldroad` and `newroad` arrays **using a parallel loop**. With a very long road (e.g. at least ten million cells), what is the effect on performance for small and large numbers of threads? Do you understand what is happening here?
4. Minimise the overhead of creating parallel regions by enclosing the entire iteration loop with a single parallel region. What is the effect on performance? Note that this is **very challenging**, e.g. you will now need to implement `updateroad()` using orphaned directives.

5 Hybrid MPI/OpenMP

It should be quite simple to introduce OpenMP directives into the MPI code in exactly the same way as the serial code.

1. Set the length of the road to include a large power of two (e.g. use 102400) so you have more freedom to vary the number of processes.
2. Compare performance for different numbers of processes or threads on the same number of cores. For example, on 2 nodes with a total of 48 cores you could use: 48 processes (P) with 1 thread per process (T); ($P = 24, T = 2$); ($P = 12, T = 4$); ...; ($P = 2, T = 24$).