



# Introduction to Monte Carlo (MC) methods



## Why Scientists like to gamble



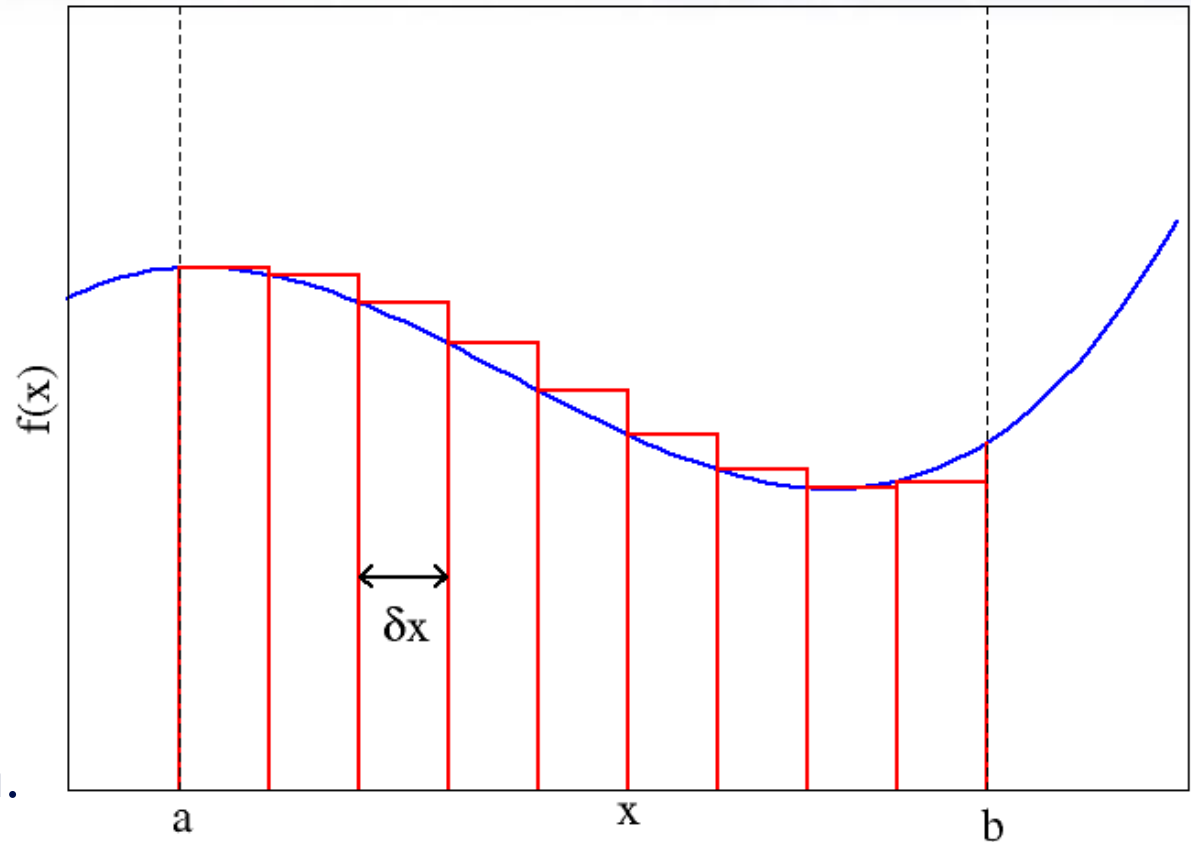
- Integration by random numbers
  - Why?
  - How?
- Uncertainty, Sharply peaked distributions
  - Importance sampling
- Markov Processes and the Metropolis algorithm
- Examples
  - statistical physics
  - finance
  - weather forecasting

Tile area with strips of height  $f(x)$  and width  $\delta x$

Analytical:

$$\delta x \rightarrow dx \rightarrow 0$$

Numerical: integral replaced with a sum.

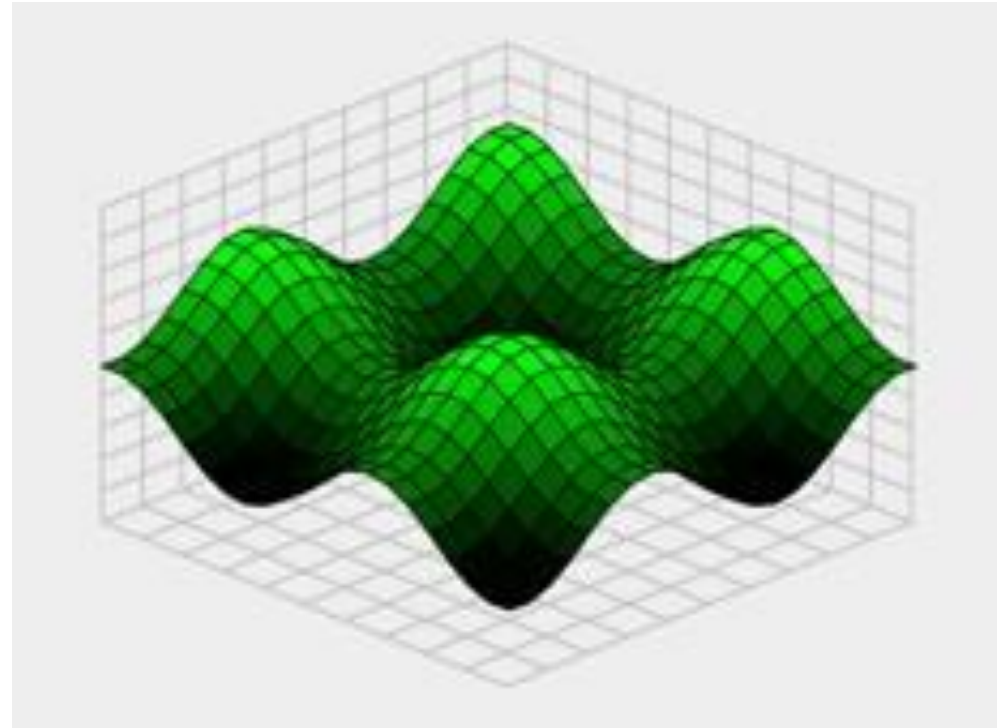


Uncertainty depends on size of  $\delta x$  (**N points**) and order of scheme, (Trapezoidal, Simpson, etc)

1d integration  
requires  $N$  points

2d integration  
requires  $N^2$

Problem of dimension  
 $m$  requires  $N^m$



***Curse of dimensionality***

Area of circle =  $\pi r^2$

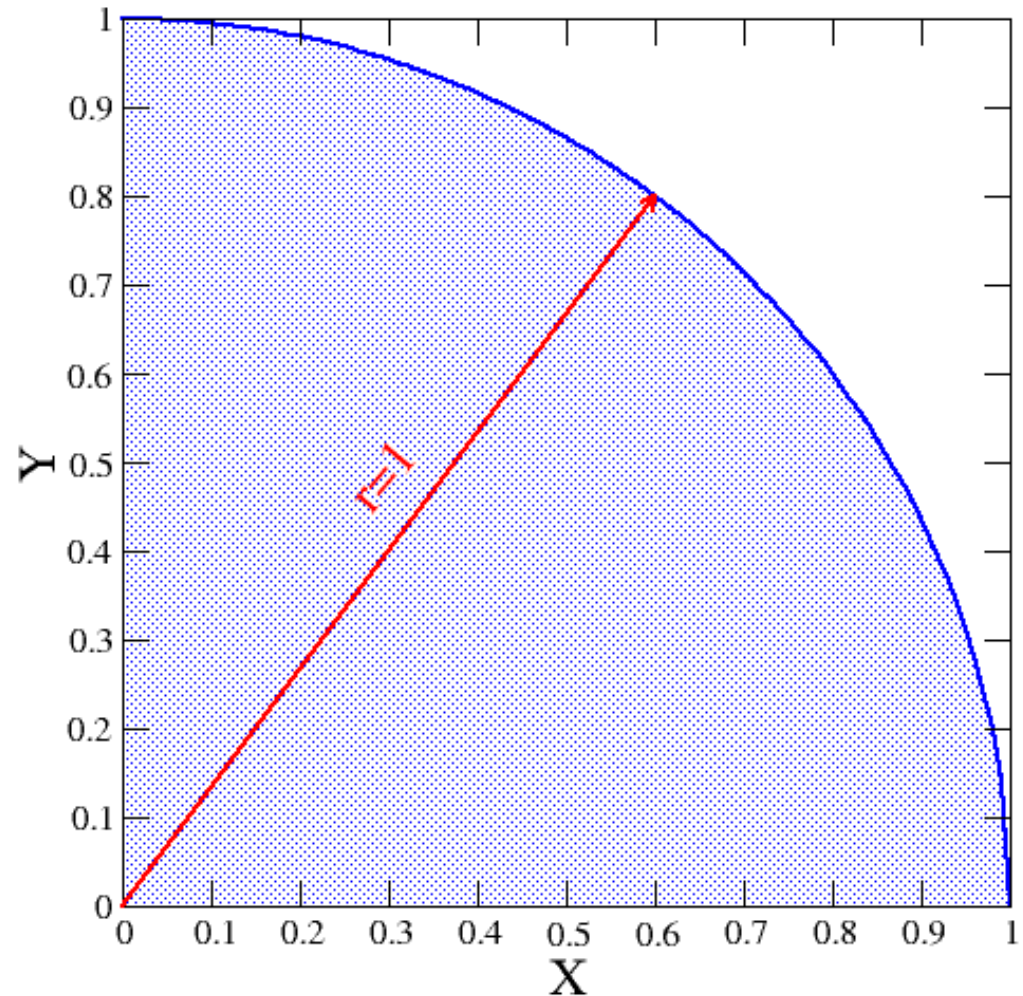
Area of unit square,  $s = 1$

Area of shaded arc,

$$c = \pi/4$$

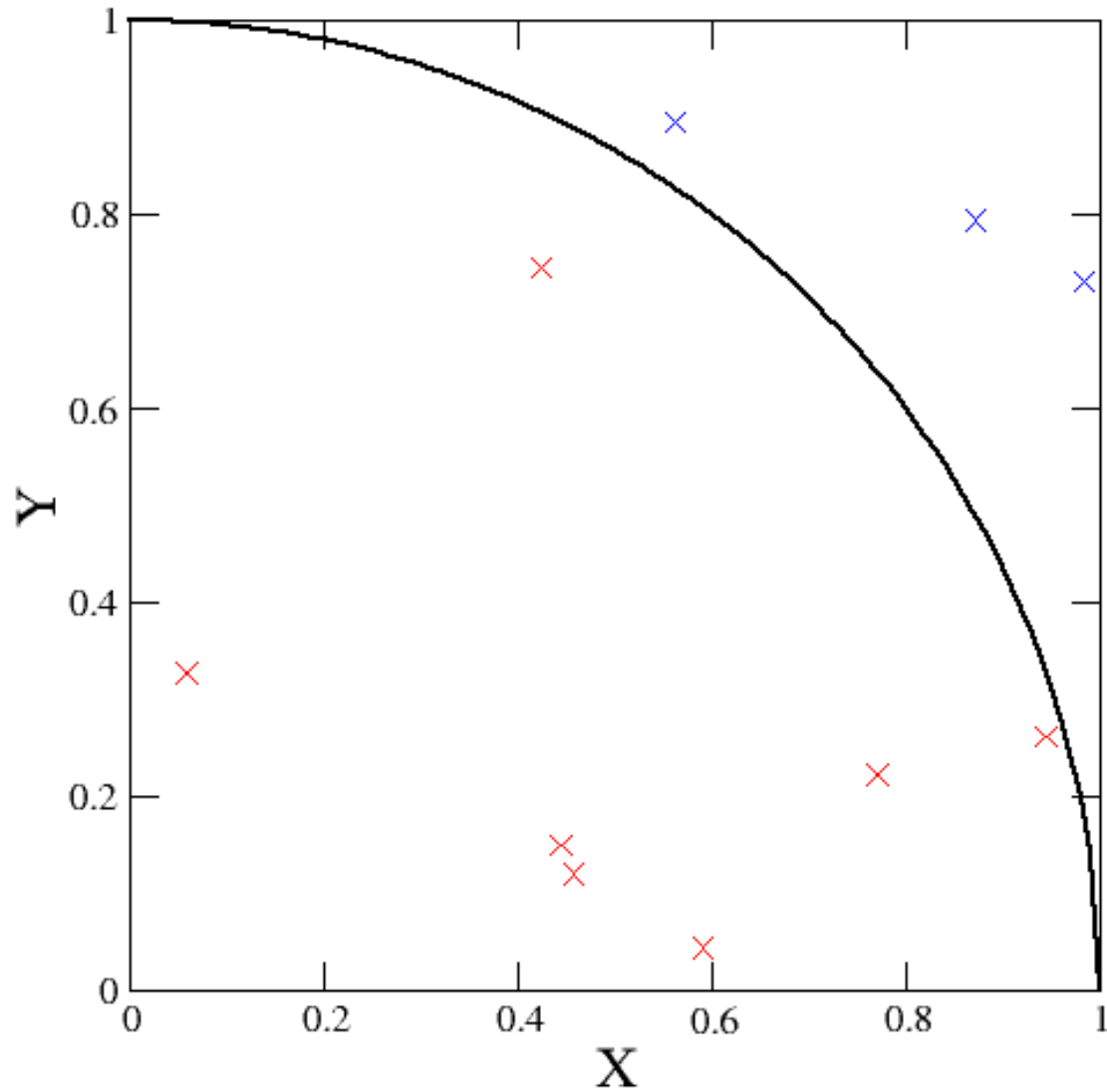
$$c/s = \pi/4$$

Estimate ratio of shaded to non-shaded area to determine  $\pi$



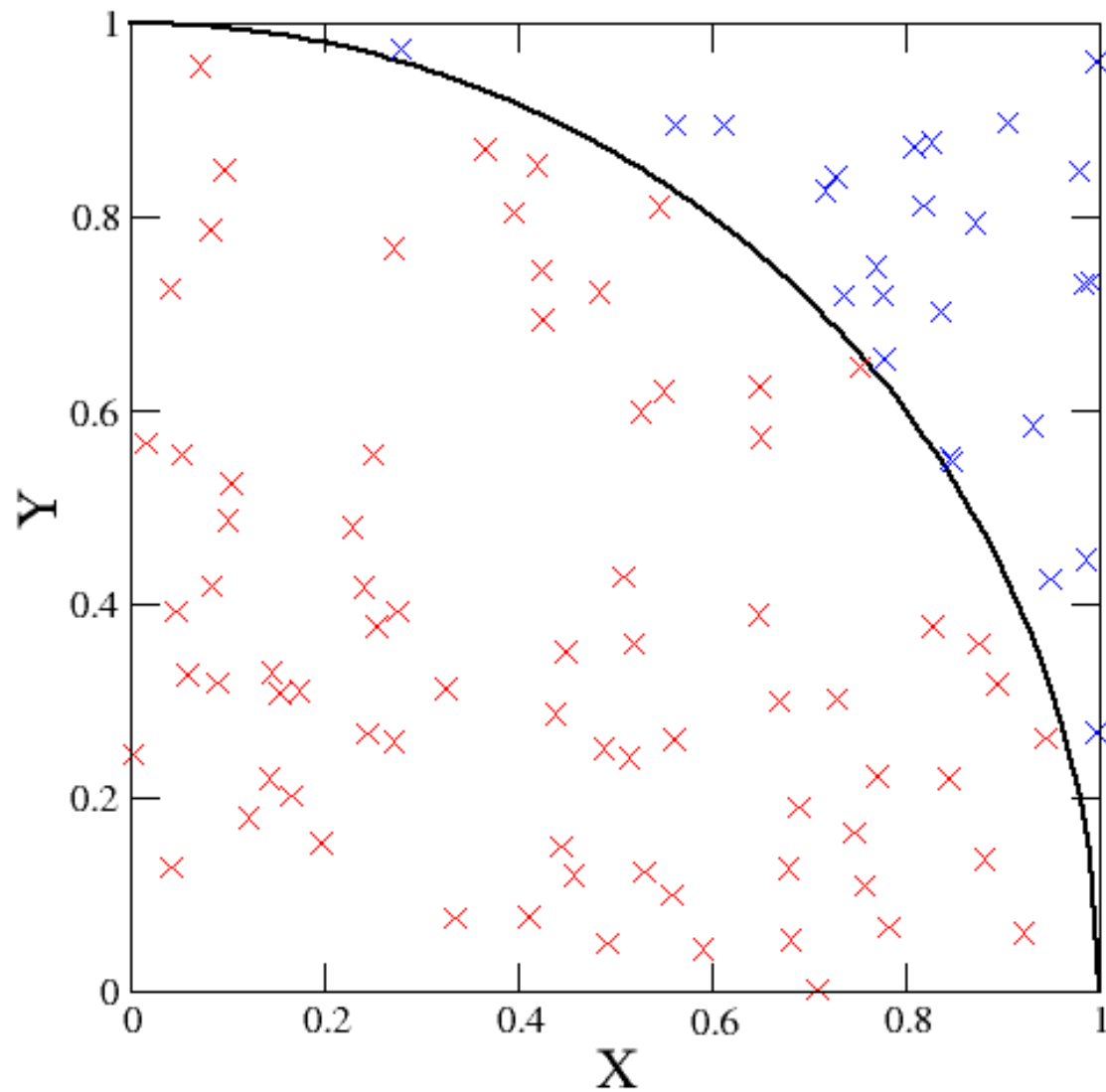
- `y = rand() / RAND_MAX // float {0.0:1.0}`
- `x = rand() / RAND_MAX`
- `P=x*x + y*y // x*x + y*y = 1 eqn of circle`
- `If (P<=1)`
  - `isInCircle`
- `Else`
  - `IsOutCircle`
- `Pi=4*isInCircle / (isOutCircle+isInCircle)`

$\pi = 2.8$

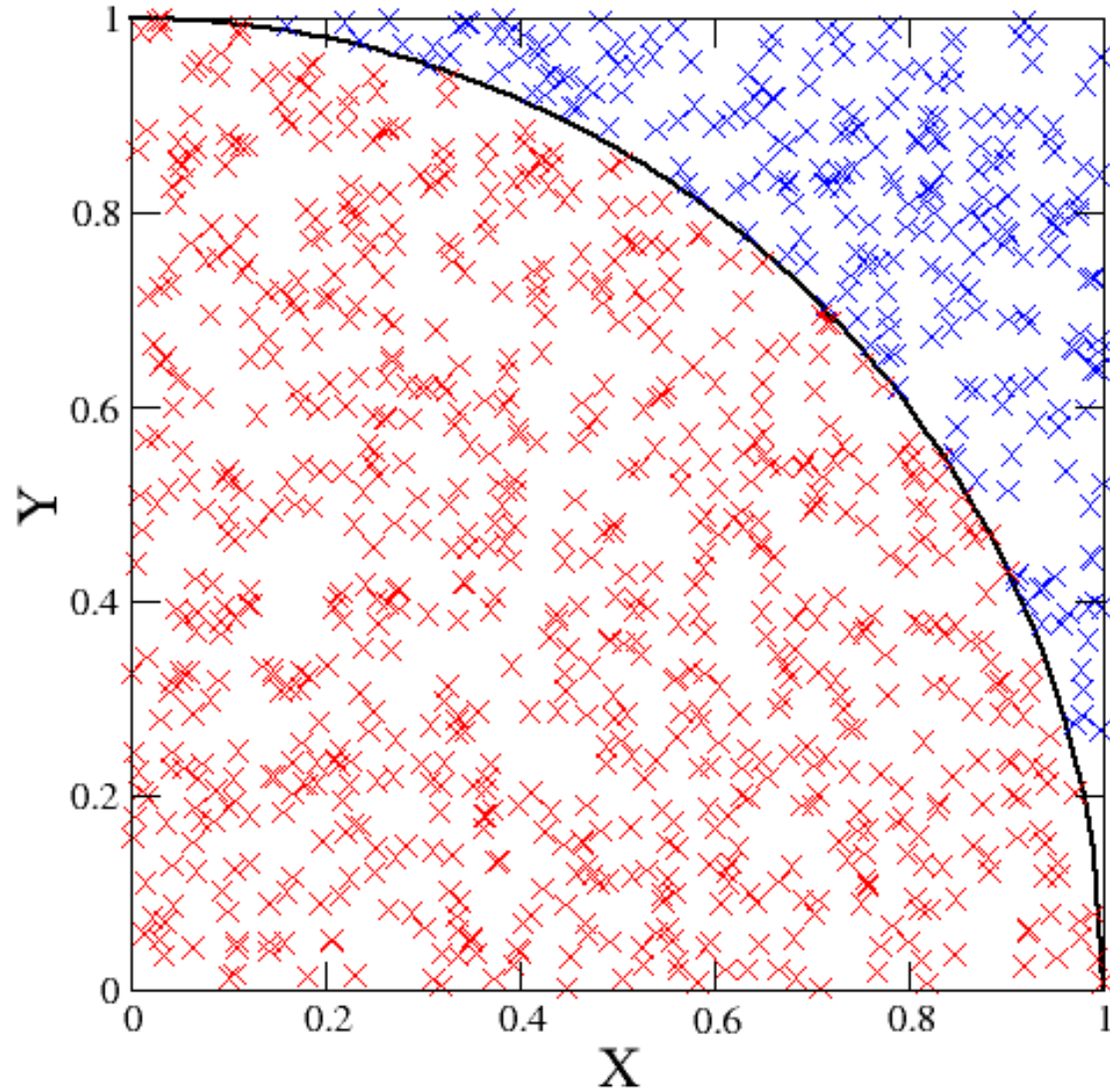




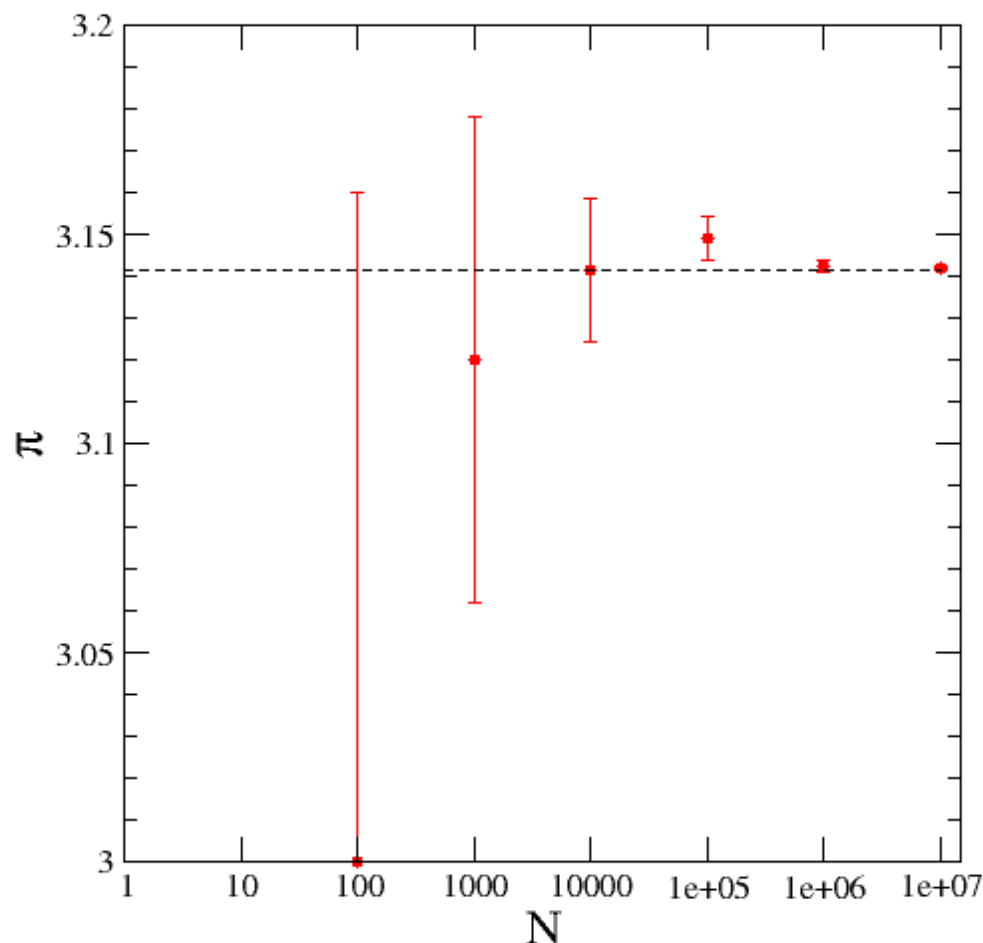
$\pi = 3.0$



$\pi = 3.12$



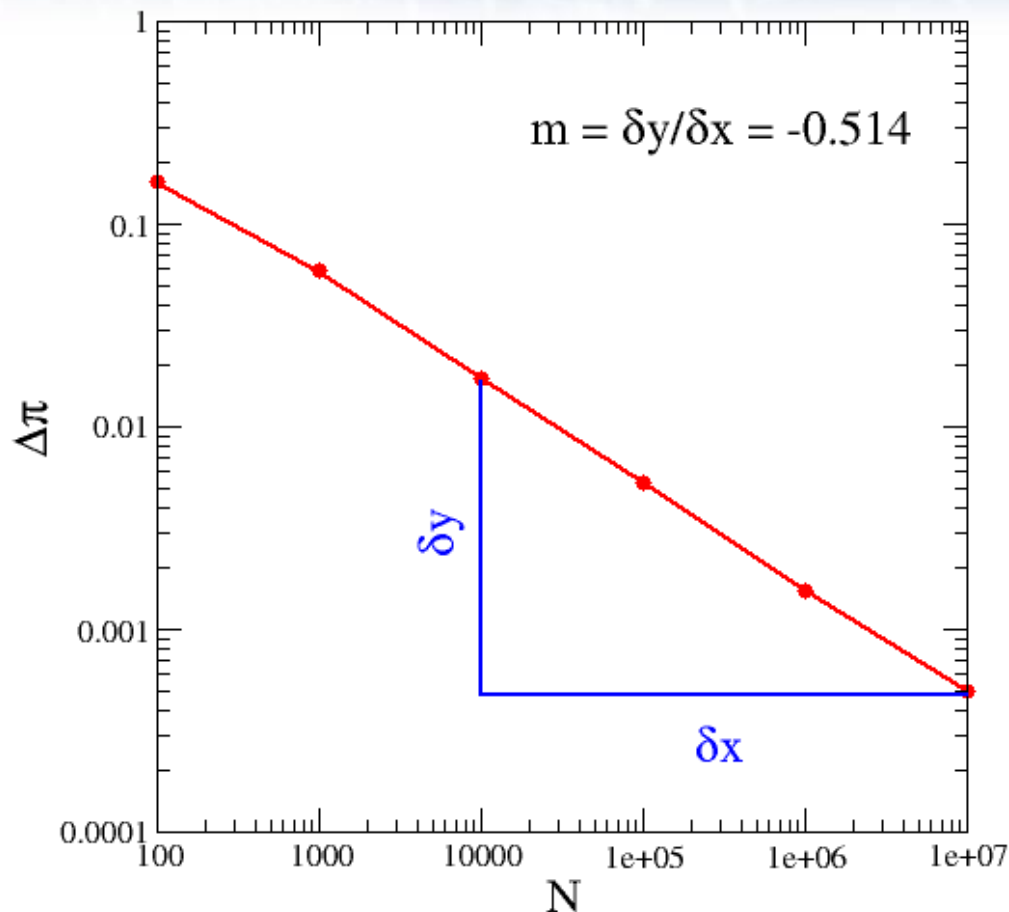
- Stochastic method
  - Statistical **uncertainty**
- Estimate this
  - Run each measurement 100 times with different random number sequences
  - Determine the **variance** of the distribution
$$\sigma^2 = (\bar{x} - x)^2 / k$$
  - Standard deviation is  $\sigma$
  - How does the uncertainty scale with N, number of samples



- Log-log plot  
 $y = ax^b$   
 $\log y = \log a + b \log x$
- Exponent  $b$ , is gradient
- $b \approx -0.5$
- Law of large numbers and central limit theorem

$$\Delta \sim 1/\sqrt{N}$$

True for *all* MC methods





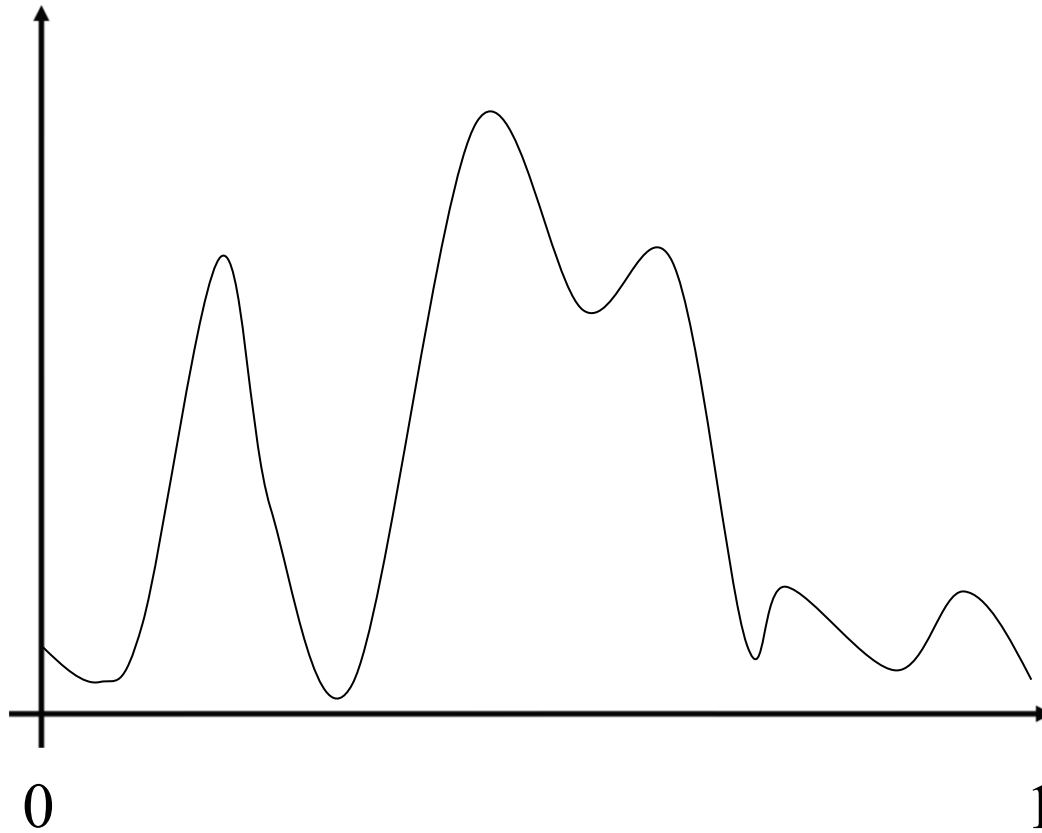
- Imagine traffic model
  - can compute average velocity for a given density
  - this in itself requires random numbers ...
- What if we wanted to know average velocity of cars over a week
  - each day has a different density of cars (weekday, weekend, ...)
  - assume this has been measured (by a man with a clipboard)

Density	Frequency
0.3	4
0.5	1
0.7	2

- Procedure:
  - run a simulation for each density to give average car velocity
  - compute average over week by weighting by probability of that density
  - i.e. velocity =  $1/7 * ( 4 * \text{velocity}(\text{density} = 0.3) + 1 * \text{velocity}(\text{density} = 0.5) + 2 * \text{velocity}(\text{density} = 0.7) )$
- In general, for many states  $x_j$  (e.g. density) and some function  $f(x_j)$  (e.g. velocity) need to compute *expectation value*  $\langle f \rangle$

$$\sum_{1}^{N} p(x_j) * f(x_i)$$

probability of  
occurrence



density of  
traffic

# Aside: A highly dimensional system



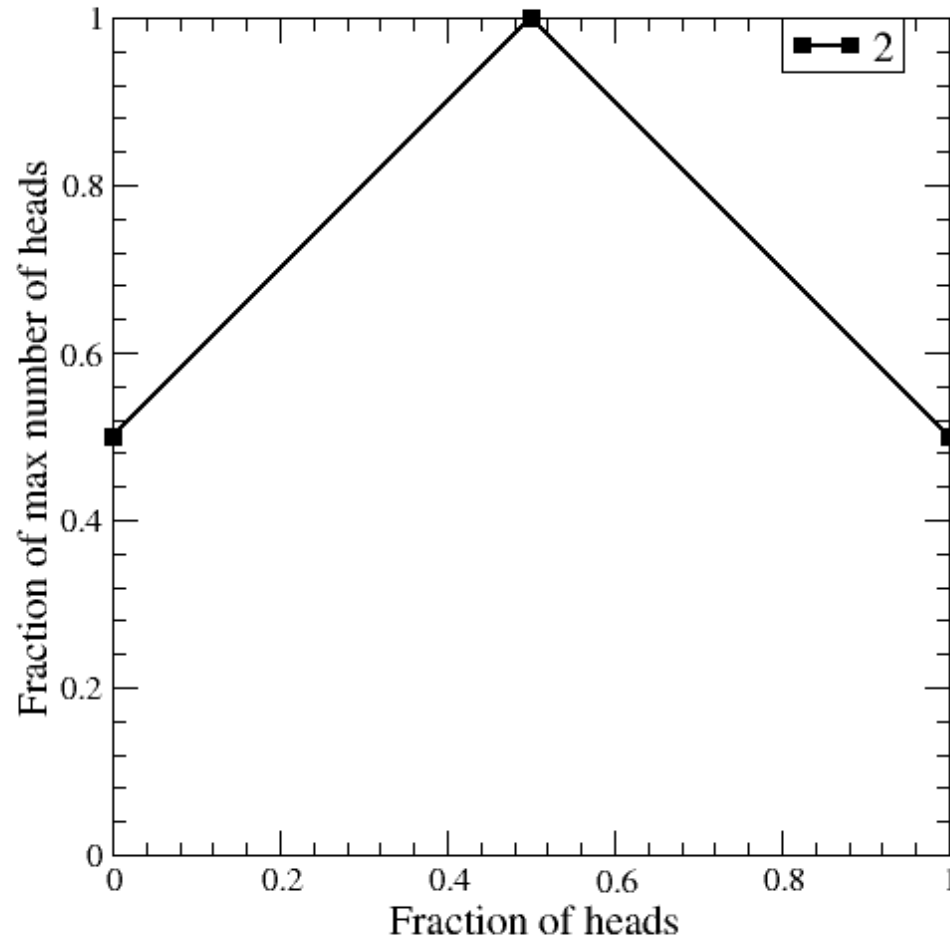


- 1 coin has 1 degree of freedom
  - Two possible states Heads and Tails
- 2 coins have 2 degrees of freedoms
  - Four possible micro-states, two of which are the same
  - Three possible states 1\*HH, 2\*HT, 1\*TT
- n coins have n degrees of freedom
  - $2^n$  microstates: n+1 states
  - Number of micro-states in each state is given by the binomial expansion coefficient

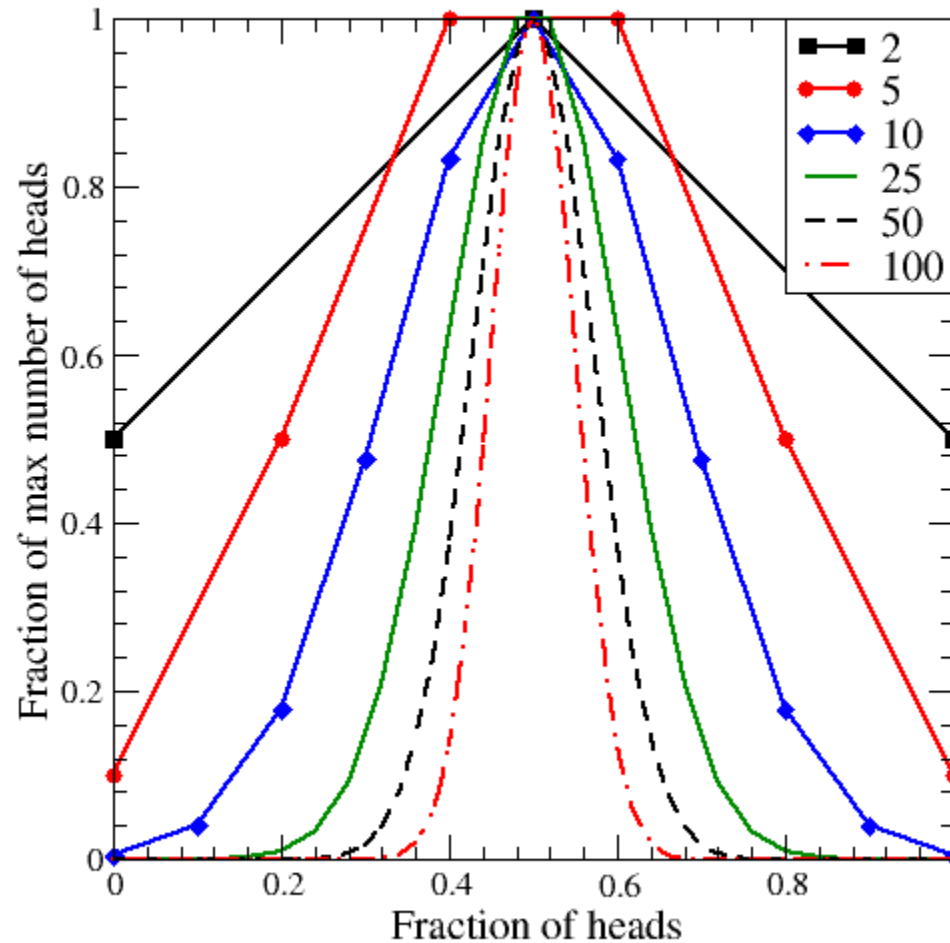
$$\Omega = 2^n = \sum_{r=0}^n {}^r C_n H^r T^{n-r}$$

$${}^r C_n = \frac{n!}{r!(n-r)!}$$

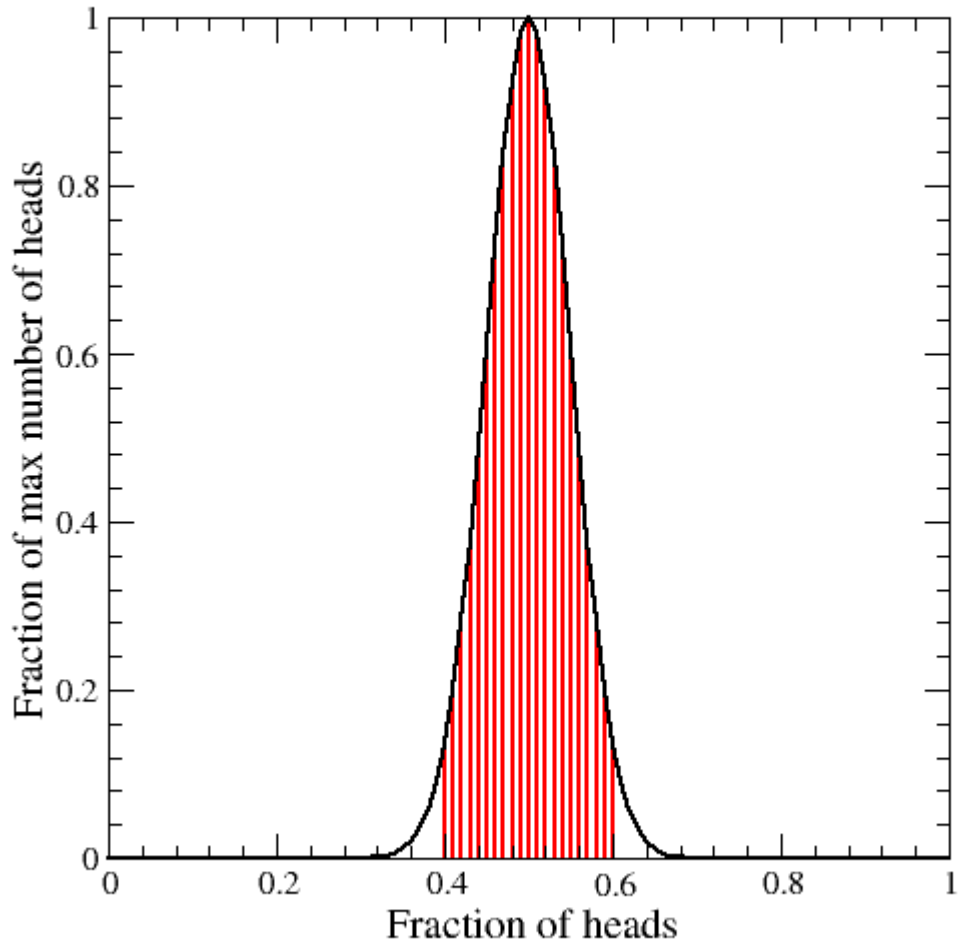
Probability distribution



Probability distribution



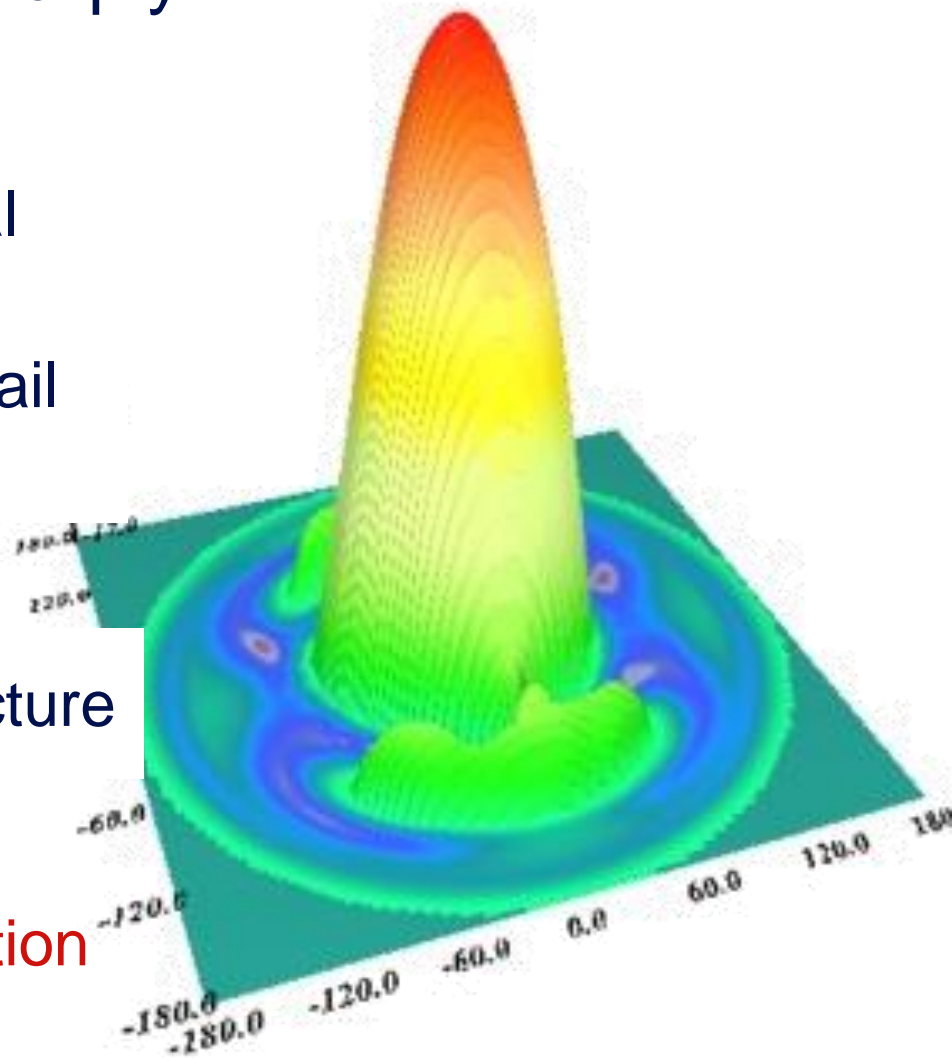
Probability distribution



- 96.48% of all possible outcomes lie between 40 – 60 heads



- The **distribution** is often sharply peaked
  - especially high-dimensional functions
  - often with fine structure detail
- Random sampling
  - $p(x_i) \sim 0$  for many  $x_i$
  - **$N$  large** to resolve fine structure
- Importance sampling
  - generate **weighted distribution**
  - proportional to probability



- With random (or uniform) sampling

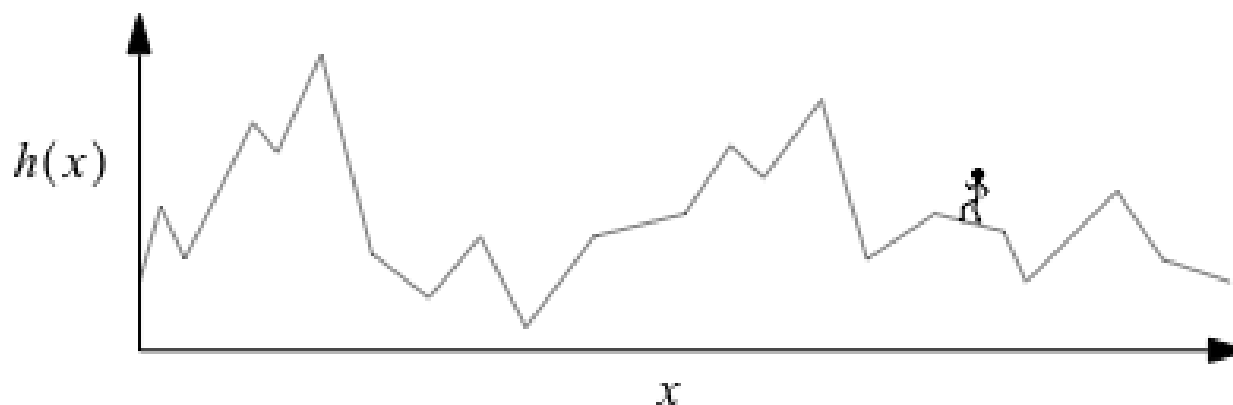
$$\langle f \rangle = \sum_1^N p(x_i) * f(x_i)$$

- but for highly peaked distributions,  $p(x_i) \sim 0$  for most cases
  - most of our measurements of  $f(x_i)$  are effectively wasted
  - large statistical uncertainty in result
- If we generate  $x_i$  with *probability proportional* to  $p(x_i)$

$$\langle f \rangle = \frac{1}{N} \sum_1^N f(x_i)$$

- all measurements contribute equally
- But how do we do this?

- Want to spend your time in areas proportional to height  $h(x)$



- walk randomly to explore all positions  $x_i$
  - if you always head up-hill or down-hill
    - get stuck at nearest peak or valley
  - if you head up-hill or down-hill with equal probability
    - you don't prefer peaks over valleys
- Strategy
    - take both up-hill and down-hill steps but with a *preference* for up-hill



AA Markov 1856-1922

- Generate samples of  $\{x_i\}$  with probability  $p(x)$
- $x_i$  no longer chosen independently
- Generate new value from old – **evolution**

$$x_{i+1} = x_i + \delta x$$

- **Accept/reject** change based on  $p(x_i)$  and  $p(x_{i+1})$

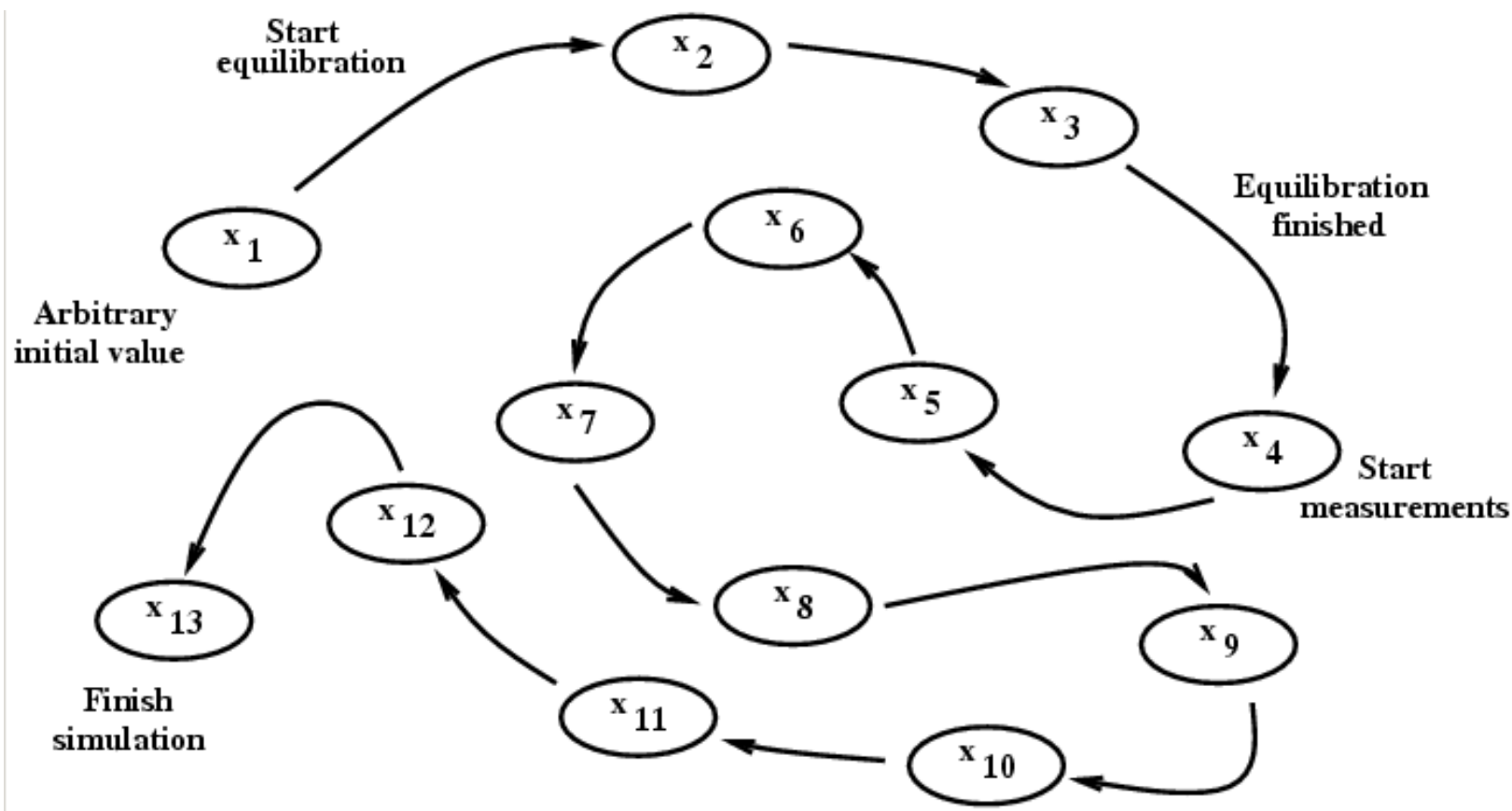
- if  $p(x_{i+1}) > p(x_i)$  then accept the change

- if  $p(x_{i+1}) < p(x_i)$  then accept **with probability**  $\frac{p(x_{i+1})}{p(x_i)}$

- **Asymptotic** probability of  $x_i$  appearing is proportional to  $p(x)$
- Need random numbers
  - to generate random moves  $\delta x$  and to do accept/reject step

- The generated sample forms a **Markov chain**
- The update process must be **ergodic**
  - Able to reach *all*  $x$
  - If the updates are non-ergodic then some states will be absent
  - Probability distribution will not be sampled correctly
  - computed expectation values will be incorrect!
- Takes some time to **equilibrate**
  - need to forget where you started from
- Accept / reject step is called the **Metropolis** algorithm



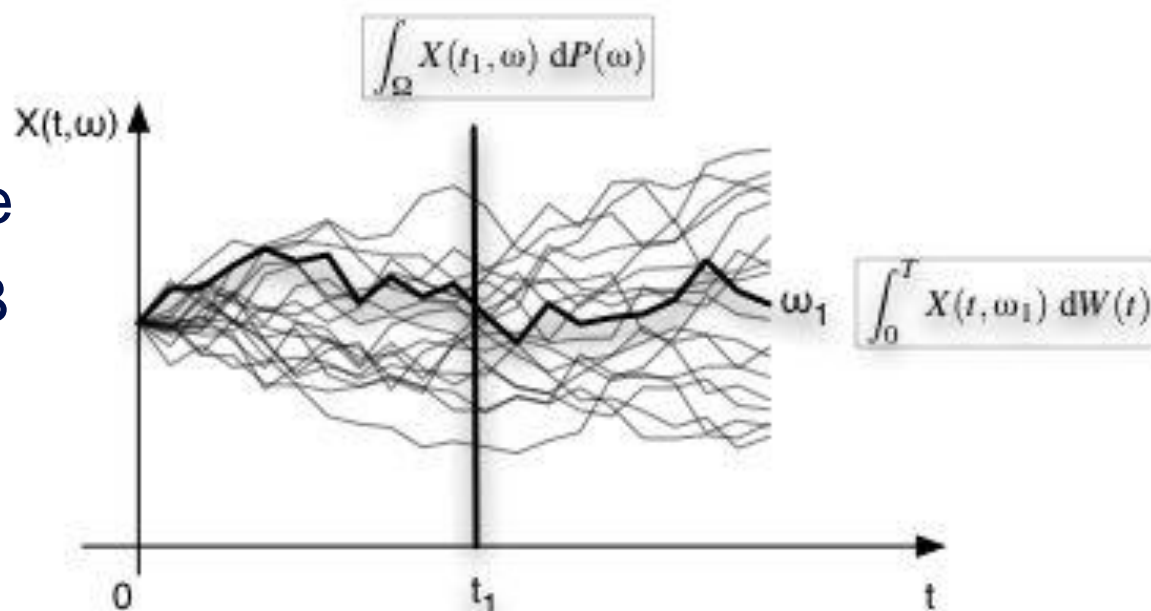


$$\langle f \rangle = \frac{1}{10} \sum_{i=4}^{13} f(x_i)$$

- Many applications use MC
- Statistical physics is an example
- Systems have extremely high dimensionality
  - e.g. positions and orientations of millions of atoms
- Use MC to generate “snapshots” or configurations of the system
- Average over these to obtain answer
  - Each individual state has no real meaning on its own
  - Quantities determined as averages across all the states

- Used to price *options*
- An option is a **contract**, holder has the *right*
  - buy an asset – *call*
  - sell an asset – *put*
  - at some time in the future (T)
  - For a predetermined price (*strike* price) X
- Terminal pay off for the holder is then
$$\max(\pm(S_T - X), 0)$$
  - where  $S_T$  is the price of the underlying asset at time T
  - $\pm$  call/put
- How much should the option cost?

- Price model called Black-Scholes equation
  - Partial differential equation
  - based on geometric brownian motion (GMB) of underlying asset
- Assumes a “perfect” market
  - markets are not perfect, especially during crashes!
  - Many extensions
  - area of active research
- Use MC to generate many different GMB paths
  - statistically analyse ensemble





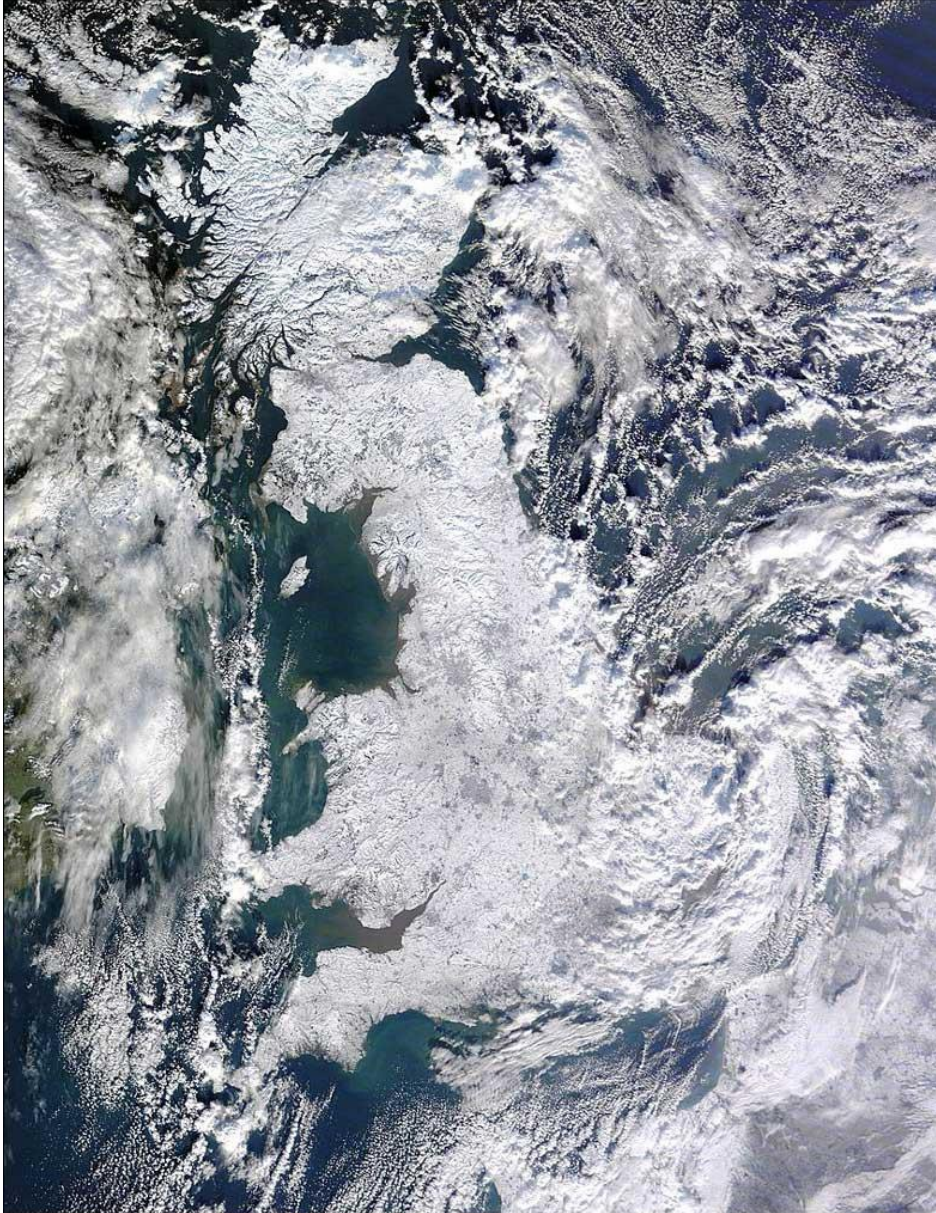


Image taken by  
NASA's Terra  
Satellite  
7<sup>th</sup> January 2010

Britain in the grip of  
a very cold spell of  
weather



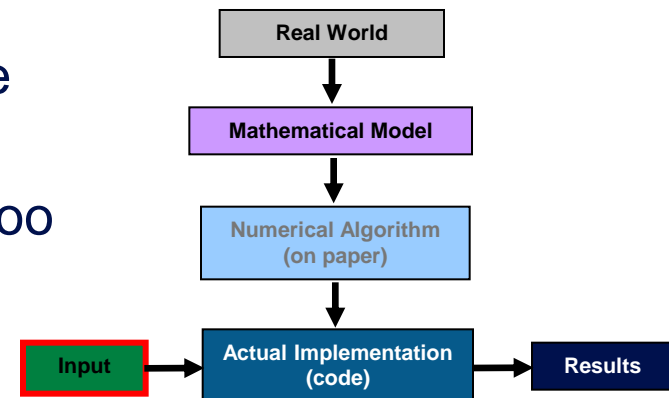
- Weather forecasts used by the media in the UK (e.g. BBC news) are generated by the UK Met office
  - Code is called the Unified Model
  - Same code runs climate model and weather forecast
  - Can cover the whole globe



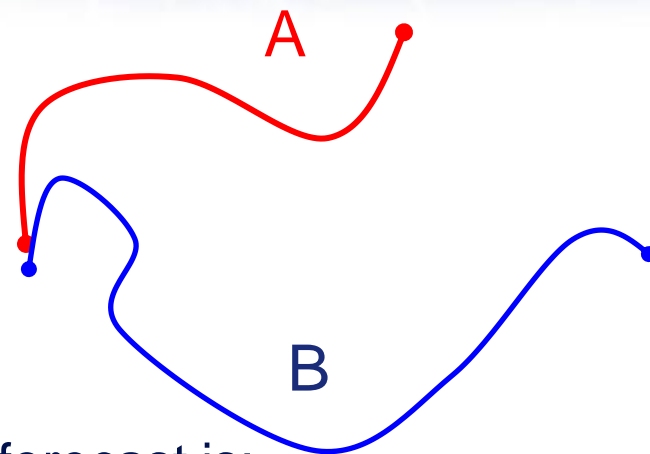
- Newest supercomputer
  - Cray XC40
  - almost half a million processor-cores
  - weighs 140 tonnes

(<http://www.bbc.co.uk/news/science-environment-29789208>)

- The equations are extremely sensitive to initial conditions
  - Small changes in the initial conditions result in large changes in outcome
- Discovered by Edward Lorenz *circa* 1960
  - 12 variable computer model
  - Minute variations in input parameters
  - Resulted in grossly different weather patterns
- The Butterfly effect
  - The flap of a butterfly's wings can effect the path of a tornado
  - My prediction is wrong because of effects too small to see

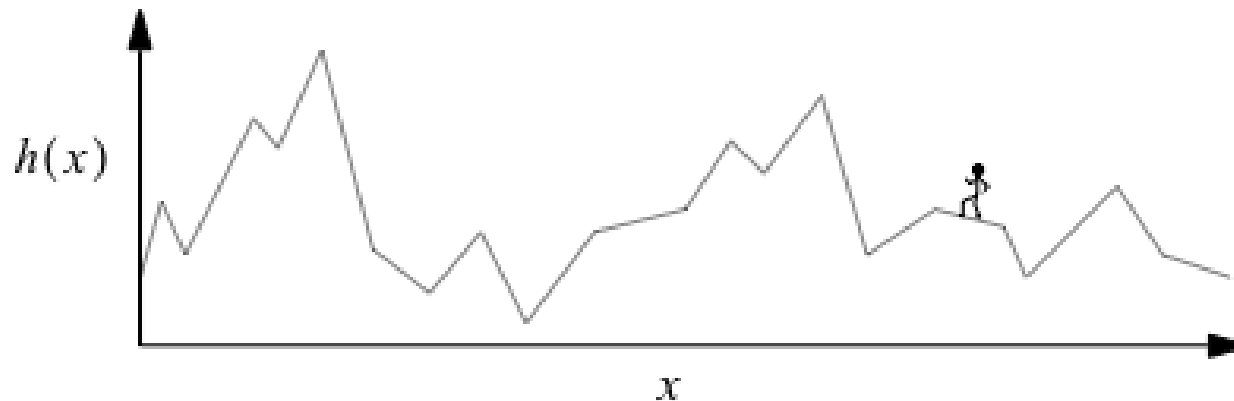


- A Chaotic system evolves to very different states from close initial states
  - no discernible pattern
- We can use this to estimate how reliable our forecast is:
- Perturb the initial conditions
  - Based on uncertainty of measurement
  - Run a new forecast
- Repeat many times (random numbers to do perturbation)
  - Generate an “ensemble” of forecasts
  - Can then estimate the probability of the forecast being correct
- If we ran 100 simulations and 70 said it would rain
  - probability of rain is 70%
  - called **ensemble** weather forecasting



- Optima of function rather than averages
- Often need to minimise or maximise functions of many variables
  - minimum distance for travelling salesman problem
  - minimum error for a set of linear equations
- Procedure
  - take an initial guess
  - successively update to progress towards solution
- What changes should be proposed?
  - could reduce/increase the function with each update (steepest descent/ascent) ...
  - ... but this will only find the local minimum/maximum

- Add a random component to updates
- Sometimes make "bad" moves
  - possible to escape from local minima
  - but want more up-hill steps than down-hill ones
- Hill-walking example
  - find the highest peak in the Alps by maximising  $h(x)$





- Monte Carlo technique applied to optimisation
- Analogy with Metropolis and Statistical Mechanics
- Initial “high-temperature” phase
  - accept both up-hill and down-hill steps to explore the space
- Intermediate phase
  - start to prefer up-hill steps to look for highest mountain
- Final “zero-temperature” phase
  - only accept up-hill steps to locate the peak of the mountain
- A lot of freedom in how you vary the temperature ...

- Random numbers used in many simulations
- Mainly to efficiently sample a large space of possibilities
- One state generated from another: Markov Chain
  - Metropolis algorithm gives a guided random walk
- Real simulations can require trillions of random numbers!
  - parallelisation introduces additional complexities ...