



Advanced Parallel Programming

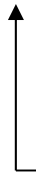
Derived Datatypes

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- Lecture will cover
 - derived datatypes
 - memory layouts
 - vector datatypes
 - floating vs fixed datatypes
 - subarray datatypes

$x[i][j]$

j



i

$x(i, j)$

$x[0][3]$	$x[1][3]$	$x[2][3]$	$x[3][3]$
$x[0][2]$	$x[1][2]$	$x[2][2]$	$x[3][2]$
$x[0][1]$	$x[1][1]$	$x[2][1]$	$x[3][1]$
$x[0][0]$	$x[1][0]$	$x[2][0]$	$x[3][0]$

$x(1,4)$	$x(2,4)$	$x(3,4)$	$x(4,4)$
$x(1,3)$	$x(2,3)$	$x(3,3)$	$x(4,3)$
$x(1,2)$	$x(2,2)$	$x(3,2)$	$x(4,2)$
$x(1,1)$	$x(2,1)$	$x(3,1)$	$x(4,1)$

- MPI has a number of pre-defined datatypes
 - eg **MPI_INT / MPI_INTEGER, MPI_FLOAT / MPI_REAL**
 - user passes them to send and receive operations
- For example, to send 4 integers from an array x

C: `int[10];`

F: `INTEGER x(10)`



`MPI_Send(x, 4, MPI_INT, ...);`

`MPI_SEND(x, 4, MPI_INTEGER, ...)`



- Can send different data by specifying different buffer

```
MPI_Send(&x[2], 4, MPI_INT, ...);
```

```
MPI_SEND(x(3), 4, MPI_INTEGER, ...)
```



- but can only send a single block of contiguous data

- Can define new datatypes called *derived types*

- various different options in MPI
- we will use them to send data with gaps in it: a **vector type**
- other MPI derived types correspond to, for example, C structs

- Contiguous type

```
MPI_Datatype my_new_type;  
MPI_Type_contiguous(count=4, oldtype=MPI_INT, newtype=&my_new_type);  
MPI_Type_commit(&my_new_type);
```

```
INTEGER MY_NEW_TYPE  
CALL MPI_TYPE_CONTIGUOUS(4, MPI_INTEGER, MY_NEW_TYPE, IERROR)  
CALL MPI_TYPE_COMMIT(MY_NEW_TYPE, IERROR)
```

```
MPI_Send(x, 1, my_new_type, ...);
```

```
MPI_SEND(x, 1, MY_NEW_TYPE, ...)
```



- Vector types correspond to patterns such as



C: $\mathbf{x}[16]$

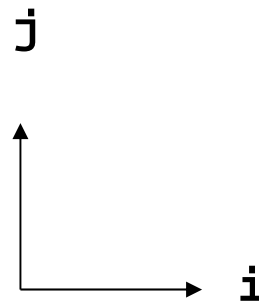
F: $\mathbf{x}(16)$

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
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C: $\mathbf{x}[4][4]$

F: $\mathbf{x}(4,4)$

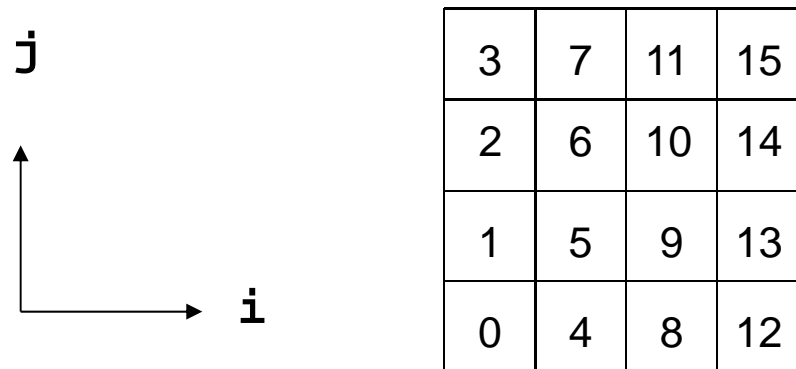
4	8	12	16
3	7	11	15
2	6	10	14
1	5	9	13



13	14	15	16
9	10	11	12
5	6	7	8
1	2	3	4

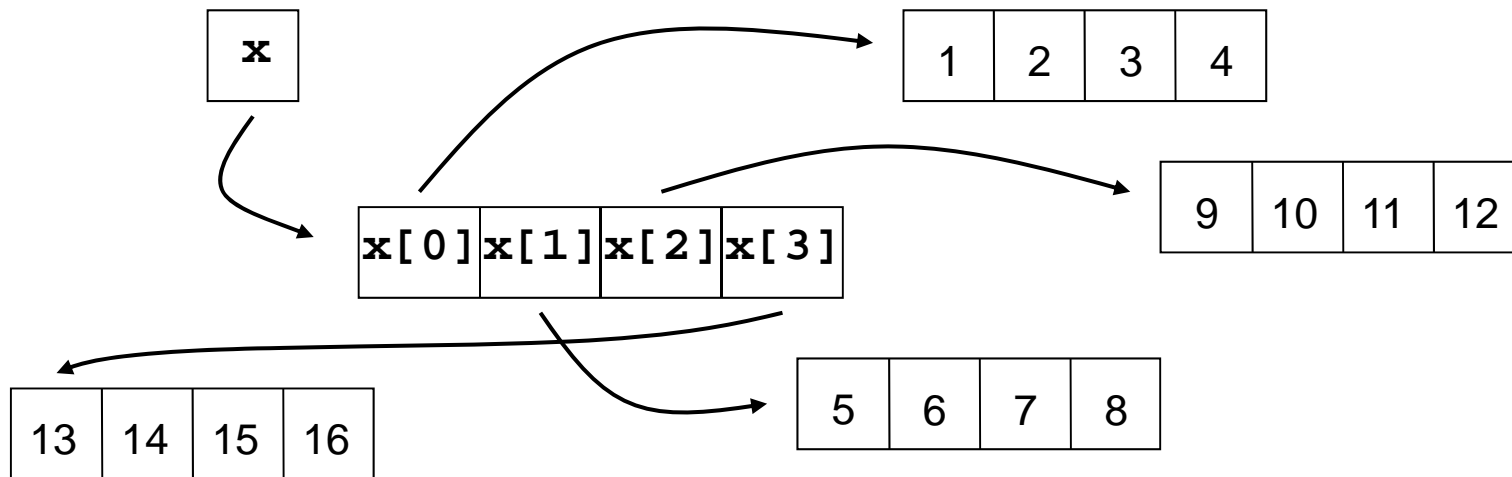
- Data is contiguous in memory
 - different conventions in C and Fortran
 - for statically allocated C arrays $\mathbf{x} == \&\mathbf{x}[0][0]$

- I use C convention for *process* coordinates, even in Fortran
 - ie processes always ordered as for C arrays
 - and array indices also start from 0
- Why?
 - this is what is returned by MPI for cartesian topologies
 - turns out to be convenient for future exercises
- Example: *process* rank layout on a 4x4 *process* grid
 - rank 6 is at position (1,2), ie $i = 1$ and $j = 2$, for C and Fortran



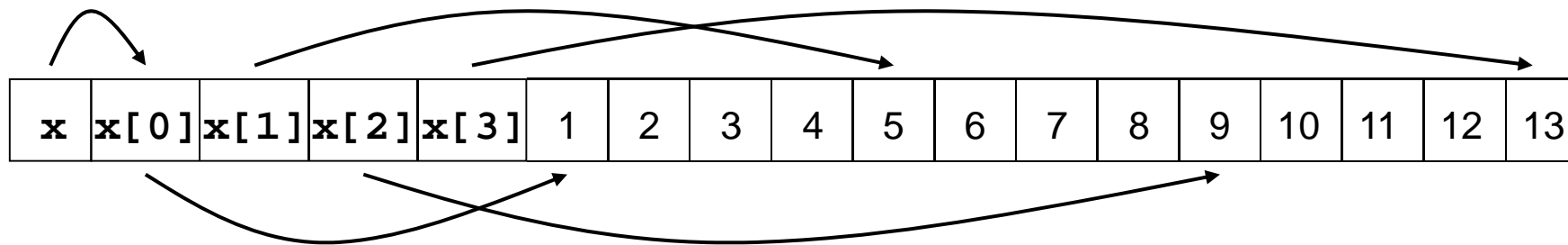
Aside: Dynamic Arrays in C

```
float **x = (float **) malloc(4, sizeof(float *));  
  
for (i=0; i < 4; i++)  
{  
    x[i] = (float *) malloc(4, sizeof(float));  
}
```



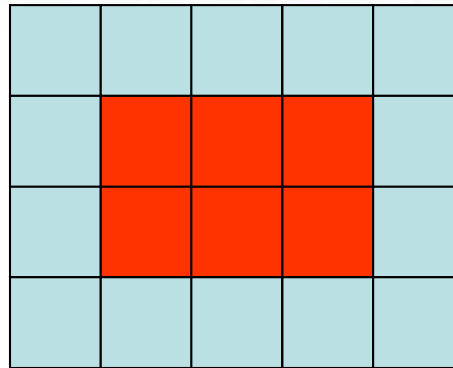
- Data non-contiguous, and **x** **!=** **&x[0][0]**
 - cannot use regular templates such as vector datatypes
 - cannot pass **x** to any MPI routine

```
float **x = (float **) arralloc(sizeof(float), 2, 4, 4);  
/* do some work */  
free((void *) x);
```

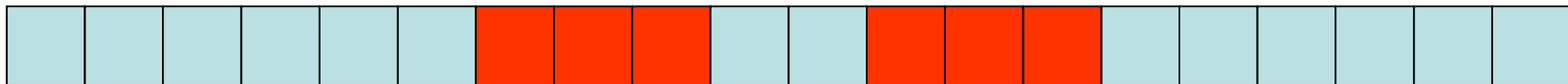
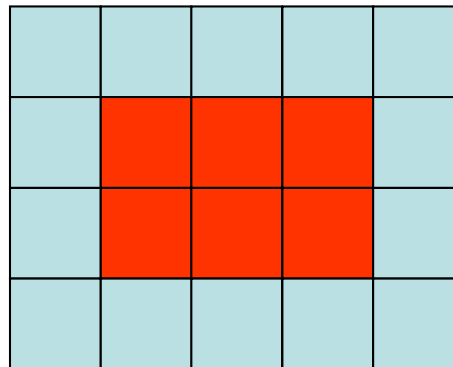


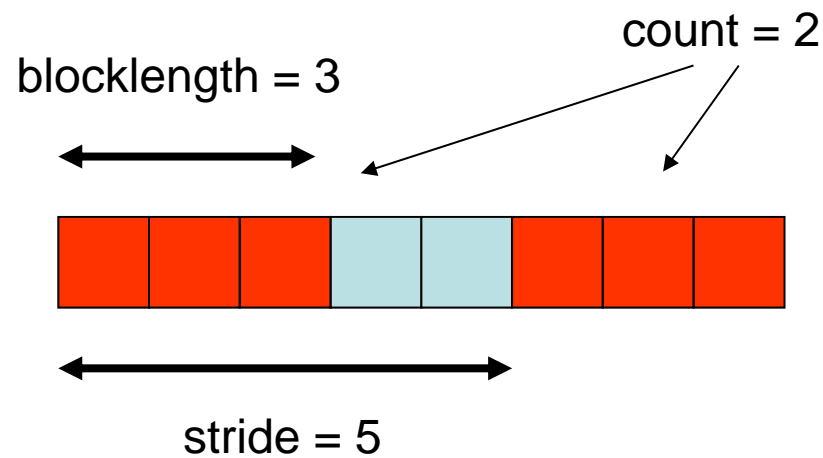
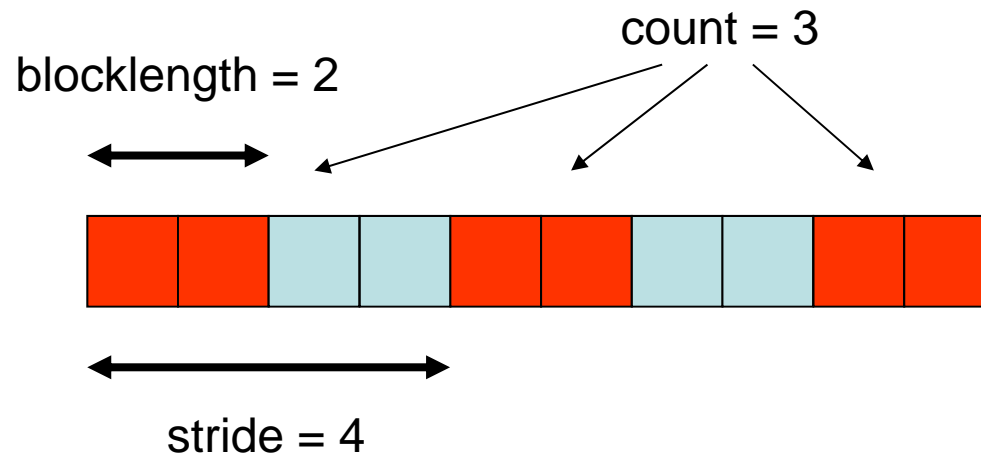
- Data is now contiguous, but still $\mathbf{x} \neq \&\mathbf{x}[0][0]$
 - can now use regular template such as vector datatype
 - must pass $\&\mathbf{x}[0][0]$ (start of contiguous data) to MPI routines
 - see `PSMA-arralloc.tar` for example of use in practice
- Will illustrate all calls using $\&\mathbf{x}[i][j]$ syntax
 - correct for both static and (contiguously allocated) dynamic arrays

C: `x[5][4]`



F: `x(5,4)`





```
MPI_Type_vector(int count, int blocklength, int stride,  
                MPI_Datatype oldtype, MPI_Datatype *newtype);
```

```
MPI_TYPE_VECTOR(COUNT, BLOCKLENGTH, STRIDE,  
                OLDTYPE, NEWTYPE, IERR)
```

```
INTEGER COUNT, BLOCKLENGTH, STRIDE, OLDTYPE
```

```
INTEGER NEWTYPE, IERR
```

```
MPI_Datatype vector3x2;
```

```
MPI_Type_vector(3, 2, 4, MPI_FLOAT, &vector3x2)
```

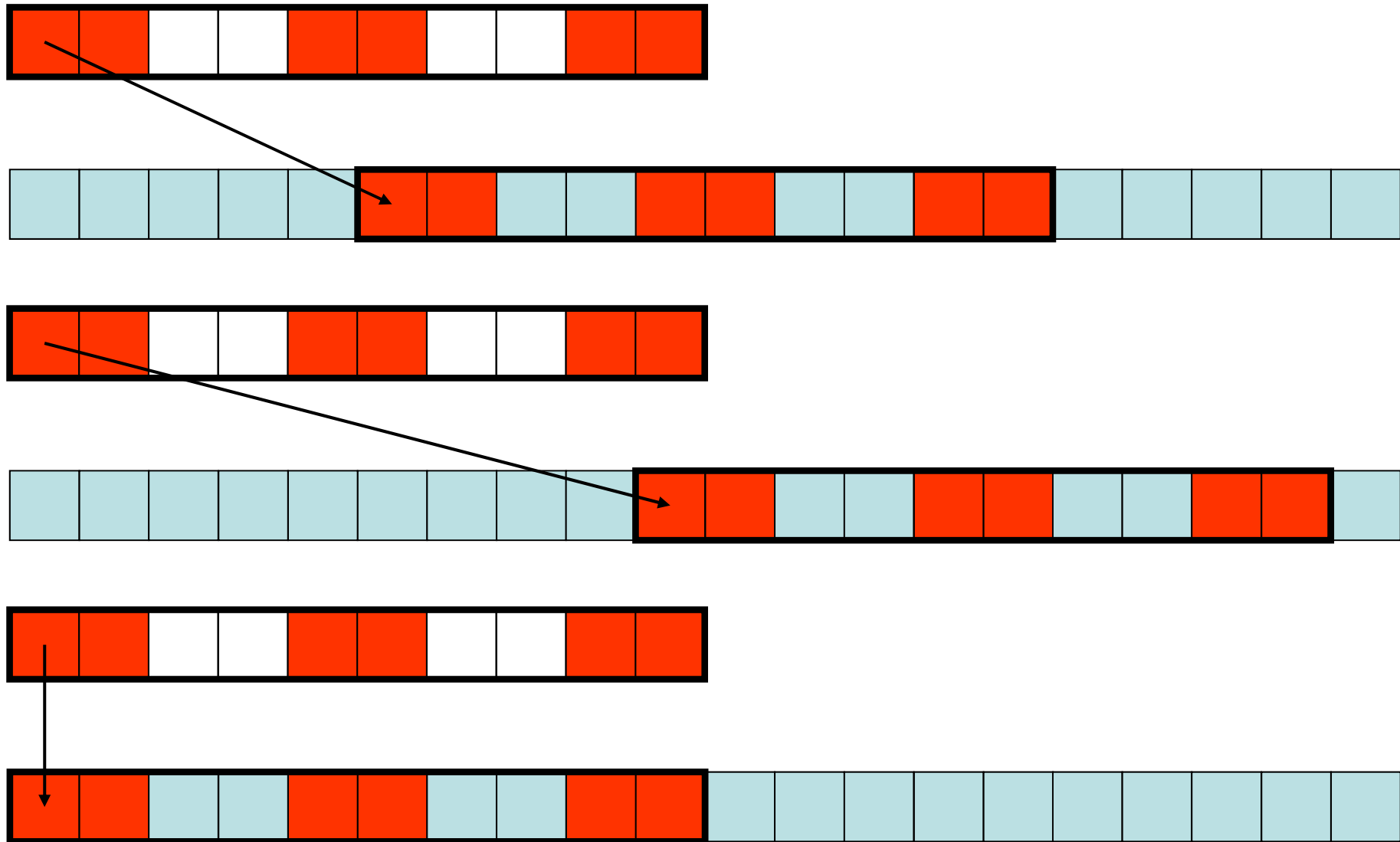
```
MPI_Type_commit(&vector3x2)
```

```
integer vector3x2
```

```
call MPI_TYPE_VECTOR(2, 3, 5, MPI_REAL, vector3x2, ierr)
```

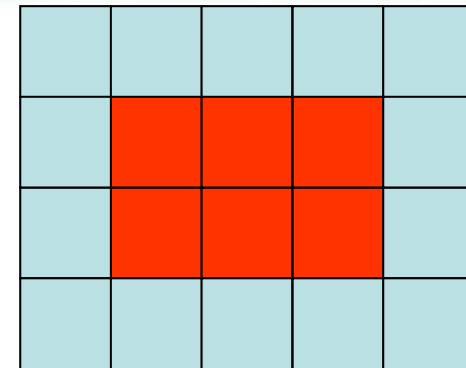
```
call MPI_TYPE_COMMIT(vector3x2, ierr)
```


Datatypes as Floating Templates

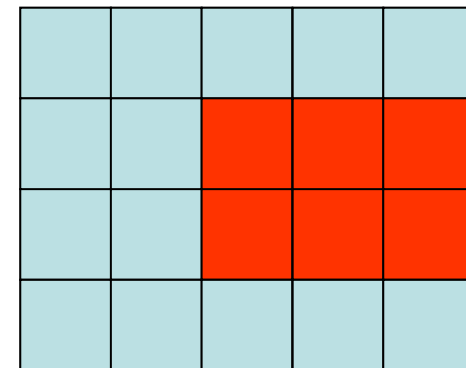


Choosing the Subarray Location

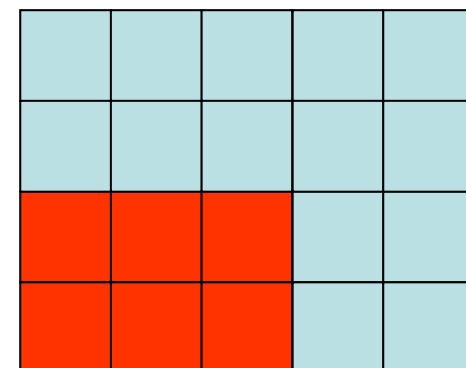
```
MPI_Send(&x[1][1], 1, vector3x2, ...);  
MPI_SEND(x(2,2) , 1, vector3x2, ...)
```



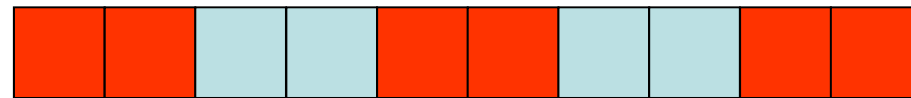
```
MPI_Send(&x[2][1], 1, vector3x2, ...);  
MPI_SEND(x(3,2) , 1, vector3x2, ...)
```



```
MPI_Send(&x[0][0], 1, vector3x2, ...);  
MPI_SEND(x(1,1) , 1, vector3x2, ...)
```



- When sending multiple datatypes
 - datatypes are read from memory separated by their extent
 - for basic datatypes, extent is the size of the object
 - for vector datatypes, extent is distance from first to last data



extent = 10*extent(basic type)



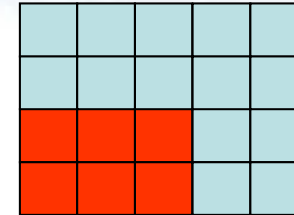
extent = 8*extent(basic type)

- Extent *does not* include trailing spaces

Sending Multiple Vectors

```
MPI_Send(&x[0][0], 1, vector3x2, ...);
```

```
MPI_SEND(x(1,1) , 1, vector3x2, ...)
```



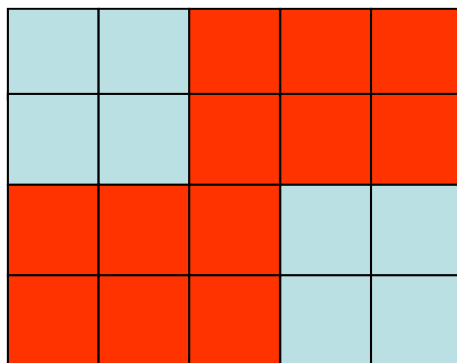
```
MPI_Send(&x[0][0], 2, vector3x2, ...);
```



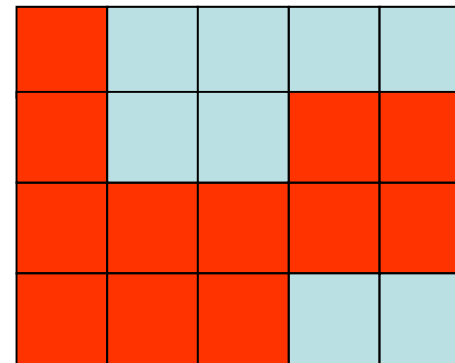
```
MPI_SEND(x(1,1) , 2, vector3x2, ...)
```



C

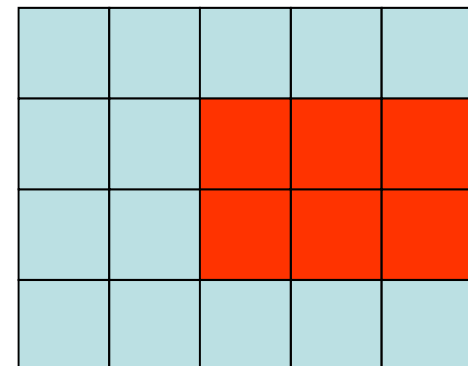


F



- Sending multiple vectors is not often useful
 - extents are not defined as you might expect for 2D arrays
- A 3D array subsection is not a vector
 - but cannot easily use 2D vectors as building blocks due to extents
 - becomes even harder for higher-dimensional arrays
- It is possible to set the extent manually
 - routine is called `MPI_Type_create_resized`
 - this is not a very elegant solution

- Vectors are floating datatypes
 - this may have some advantages, eg define a single halo datatype and use for both up and down halos
 - actual location is selected by passing address of appropriate element
 - equivalent in MPI-IO is specifying a displacement into the file
 - this will turn out to be rather clumsy
- Fixed datatype
 - always pass starting address of array
 - datatype encodes both the shape and position of the subarray
- How do we define a fixed datatype?
 - requires a datatype with leading spaces
 - difficult to do with vectors



- A single call that defines multi-dimensional subsections
 - much easier than vector types for 3D arrays
 - datatypes are fixed
 - pass the starting address of the array to all MPI calls

```
MPI_Type_create_subarray(int ndims, int array_of_sizes[],  
    int array_of_subsizes[], int array_of_starts[],  
    int order, MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_SUBARRAY(NDIMS, ARRAY_OF_SIZES,  
    ARRAY_OF_SUBSIZES, ARRAY_OF_STARTS, ORDER,  
    OLDTYPE, NEWTYPE, IERR)
```

```
INTEGER NDIMS, ARRAY_OF_SIZES(*), ARRAY_OF_SUBSIZES(*),  
    ARRAY_OF_STARTS(*), ORDER, OLDTYPE, NEWTYPE, IERR
```

```
#define NDIMS 2
MPI_Datatype subarray3x2;
int array_of_sizes[NDIMS], array_of_subsizes[NDIMS],
    arrays_of_starts[NDIMS];

array_of_sizes[0]      = 5; array_of_sizes[1]      = 4;
array_of_subsizes[0]  = 3; array_of_subsizes[1]  = 2;
array_of_starts[0]    = 2; array_of_starts[1]    = 1;

order = MPI_ORDER_C;

MPI_type_create_subarray(NDIMS, array_of_sizes,
    array_of_subsizes, array_of_starts, order,
    MPI_FLOAT, &subarray3x2);
MPI_TYPE_COMMIT(&subarray3x2);
```

```
integer, parameter :: ndims = 2
integer subarray3x2
integer, dimension(ndims) :: array_of_sizes, array_of_subsizes,
                             arrays_of_starts

! Indices start at 0 as in C !

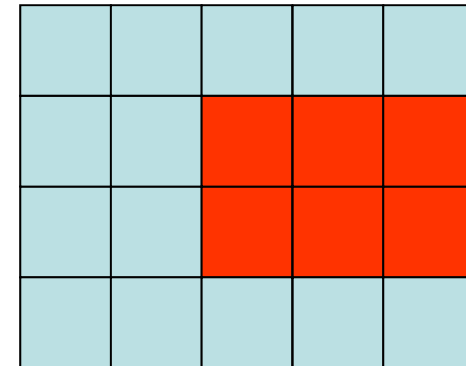
array_of_sizes(1)      = 5; array_of_sizes(2)      = 4
array_of_subsizes(1)  = 3; array_of_subsizes(2)  = 2
array_of_starts(1)    = 2; array_of_starts(2)    = 1

order = MPI_ORDER_FORTRAN

call MPI_TYPE_CREATE_SUBARRAY(ndims, array_of_sizes,
                              array_of_subsizes, array_of_starts, order,
                              MPI_REAL, subarray3x2, ierr)

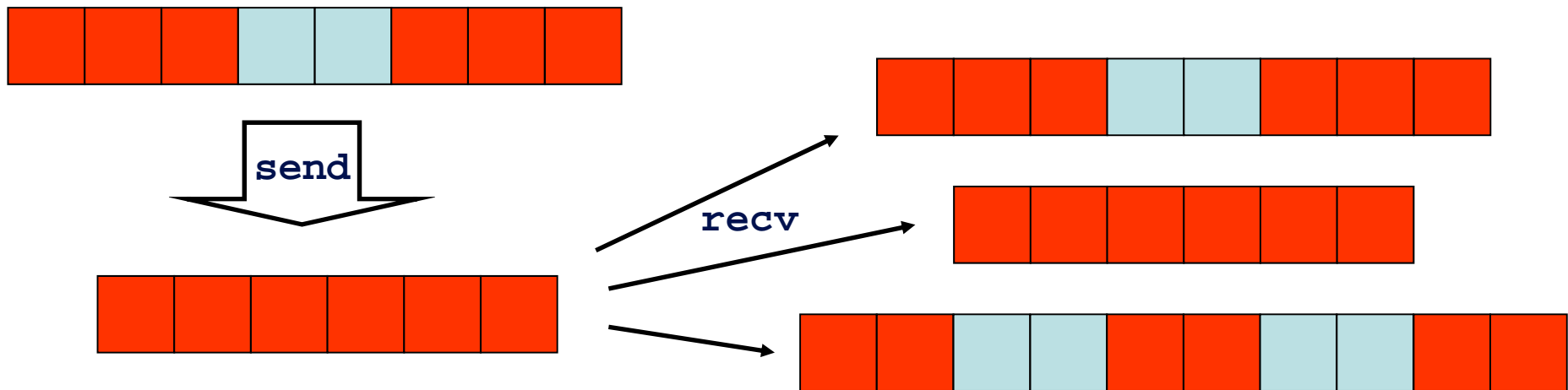
call MPI_TYPE_COMMIT(subarray3x2, ierr)
```

```
MPI_Send(&x[0][0], 1, subarray3x2, ...);  
MPI_SEND(x          , 1, subarray3x2, ...)  
MPI_SEND(x(1,1)    , 1, subarray3x2, ...)
```



- Generalisation to IO
 - each process counts from the start of the file
 - actual displacements from file origin depend on the position of the process in the process array
 - this is all already encoded in the datatype

- A datatype is defined by two attributes:
 - type signature: a list of the basic datatypes in order
 - type map: the locations (displacements) of each basic datatype
- For a receive to match a send only signatures need to match
 - type map is defined by the receiving datatype
- Think of messages being packed for transmission by sender
 - and independently unpacked by the receiver



- There is an overhead to defining a derived type
 - a real code may have many calls to the IO routines
 - no need to re-define the data types every time
 - array sizes unlikely to change: define types once at start of program
- If you do create lots of derived types in a program ...
 - they take up memory!
 - clear up the memory using `MPI_Type_free` whenever possible
- But try and avoid:
 - do loop = 1, 1000000
 - do stuff
 - define type
 - use type
 - free type
 - end do