

Message Passing Programming

Designing MPI Applications



Lecture will cover

- MPI portability
- maintenance of serial code
- general design
- debugging
- verification

MPI Portability

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Potential deadlock

- you may be assuming that MPI_Send is asynchronous
- it often is buffered for small messages
 - but threshhold can vary with implementation
- a correct code should run if you replace all MPI_Send calls with MPI_Ssend

Buffer space

- cannot assume that there will be space for MPI_Bsend
- default buffer space is often zero!
- be sure to use MPI_Buffer_Attach
 - some advice in MPI standard regarding required size



- Cannot assume data sizes or layout
 - eg C float / Fortran REAL were 8 bytes on Cray T3E
 - can be an issue when defining struct types
 - use MPI_Type_extent to find out the number of bytes
 - be careful of compiler-dependent padding for structures
- Changing precision
 - when changing from, say, float to double, must change all the MPI types from MPI_FLOAT to MPI_DOUBLE as well
- Easiest to achieve with an include file
 - eg every routine includes precision.h



Changing Precision: C

Define a header file called, eg, precision.h

- typedef float RealNumber
- #define MPI_REALNUMBER MPI_FLOAT
- Include in every function
 - #include "precision.h"
 - . . .
 - RealNumber x;
 - MPI_Routine(&x, MPI_REALNUMBER, ...);
- Global change of precision now easy
 - edit 2 lines in one file: float -> double, MPI_FLOAT -> MPI_DOUBLE

Define a module called, eg, precision

- integer, parameter :: REALNUMBER=kind(1.0e0)
- integer, parameter :: MPI_REALNUMBER = MPI_REAL
- Use in every subroutine
 - use precision
 - . . .
 - REAL(kind=REALNUMBER):: x
 - call MPI_ROUTINE(x, MPI_REALNUMBER, ...)
- Global change of precision now easy
 change 1.0e0 -> 1.0d0, MPI_REAL -> MPI_DOUBLE_PRECISION

Testing Portability

- Run on more than one machine
 - assuming the implementations are different
 - many parallel clusters will use the same open-source MPI
 - e.g. OpenMPI or MPICH2
 - running on two different mid-sized machines may not be a good test
- More than one implementation on same machine
 - eg run using both MPICH2 and OpenMPI on your laptop
 - very useful test, and can give interesting performance numbers

More than one compiler

- user@morar\$ module switch mpich2-pgi mpich2-gcc

Serial Code

- Adding MPI can destroy a code
 - would like to maintain a serial version
 - ie can compile and run identical code without an MPI library
 - not simply running MPI code with P=1!

Need to separate off communications routines

- put them all in a separate file
- provide a dummy library for the serial code
- no explicit reference to MPI in main code

Example: Initialisation

```
! parallel routine
subroutine par_begin(size, procid)
implicit none
integer :: size, procid
include "mpif.h"
call mpi_init(ierr)
call mpi_comm_size(MPI_COMM_WORLD, size, ierr)
call mpi_comm_rank(MPI_COMM_WORLD, procid, ierr)
procid = procid + 1
end subroutine par begin
```

```
! dummy routine for serial machine
subroutine par_begin(size, procid)
implicit none
integer :: size, procid
size = 1
procid = 1
end subroutine par begin
```

Example: Global Sum

```
! parallel routine
subroutine par dsum(dval)
  implicit none
  include "mpif.h"
 double precision :: dval, dtmp
  call mpi allreduce(dval, dtmp, 1, MPI_DOUBLE_PRECISION, &
                     MPI SUM, comm, ierr)
 dval = dtmp
end subroutine par dsum
! dummy routine for serial machine
subroutine par dsum(dval)
  implicit none
 double precision dval
end subroutine par dsum
```



Example Makefile

SEQSRC=\

demparams.f90 demrand.f90 demcoord.f90 demhalo.f90 \
demforce.f90 demlink.f90 demcell.f90 dempos.f90 demons.f90

$\mathsf{MPISRC} = \setminus$

demparallel.f90 \ demcomms.f90

FAKESRC=\ demfakepar.f90\ demfakecomms.f90

#PARSRC=\$(FAKESRC)
PARSRC=\$(MPISRC)

Advantages of Comms Library

Can compile serial program from same source

- makes parallel code more readable
- Enables code to be ported to other libraries
 - more efficient but less versatile routines may exist
 - eg Cray-specific SHMEM library
 - can even choose to only port a subset of the routines
- Library can be optimised for different MPIs
 eg choose the fastest send (Ssend, Send, Bsend?)





- Separate the communications into a library
- Make parallel code similar as possible to serial
 - eg use of halos in case study
 - could use the same update routine in serial and parallel
 - serial: update(new, old, M, N);
 - parallel: update(new, old, MP, NP);
 - may have a large impact on the design of your serial code
- Don't try and be too clever
 - don't agonise whether one more halo swap is really necessary
 - just do it for the sake of robustness

General Considerations

- Compute everything everywhere
 - eg use routines such as Allreduce
 - perhaps the value only really needs to be know on the master
 - but using **Allreduce** makes things simpler
 - no serious performance implications

Often easiest to make P a compile-time constant

- may not seem elegant but can make coding much easier
 - eg definition of array bounds
- put definition in an include file
- a clever Makefile can reduce the need for recompilation
 - only recompile routines that define arrays rather than just use them
 - pass array bounds as arguments to all other routines



- Parallel debugging can be hard
- Don't assume it's a parallel bug!
 - run the serial code first
 - then the parallel code with P=1
 - then on a small number of processes ...
- Writing output to separate files can be useful
 - eg log.00, log.01, log.02, for ranks 0, 1, 2, ...
 - need some way easily to switch this on and off
- Some parallel debuggers exist
 - Totalview is the leader across all largest platforms
 - Allinea DDT is becoming more common across the board

People seem to write programs DELIBERATELY to make them impossible to debug!

- my favourite: the silent program
- "my program doesn't work"
 - \$ mprun –np 6 ./program.exe
 - \$ SEGV core dumped
- where did this crash?
- did it run for 1 second? 1 hour? in a batch job this may not be obvious
- did it even start at all?

Why don't people write to the screen!!!

Program should output like this

```
$ mprun -np 6 ./program.exe
Program running on 6 processes
Reading input file input.dat ...
... done
Broadcasting data ...
... done
rank 0: x = 3
rank 1: x = 5
etc etc
Starting iterative loop
iteration 100
iteration 200
finished after 236 iterations
writing output file output.dat ...
... done
rank 0: finished
rank 1: finished
...
Program finished
```

Typical mistakes

Don't write raw numbers to the screen!

- what does this mean?
 - \$ mprun –np 6 ./program.exe
 - 1 3 5.6
 - 398.37
- programmer has written
 - \$ printf("%d %d %f\n", rank, j, x);
 - \$ write(*,*) rank, j, x

Takes an extra 5 seconds to type:

- \$ printf("rank, j, x: %d %d %f\n", rank, j, x);
- **\$** write(*,*) 'rank, j, x: ', rank, j, x
- and will save you HOURS of debugging time

Why oh why do people write raw numbers?!?!

Debugging walkthrough

My case study code gives the wrong answer

Stages:

- read data in
- distribute to processes
- update many times
 - requiring halo swaps
- collect data back
- write data out

Final stage shows the error

– but where did it first go wrong?

Common mistake

- I changed something
 - and it now works (but I don't know why)
- All is OK!
- No!
 - there is a bug
 - you MUST find it
 - if not, it will come back later to bite you HARD

Debugging is an experimental science

Where is it going wrong?

- On input?
- On distribute?
- On update?
 - on halo swaps?
 - on left/right swaps?
 - on up/down swaps?
- On collection?
- On output?

All these can be checked with simple tests

EQCC Verification: Is My Code Working?

- Should the output be identical for any P?
 - very hard to accomplish in practice due to rounding errors
 - may have to look hard to see differences in the last few digits
 - typically, results vary slightly with number of processes
 - need some way of quantifiying the differences from serial code
 - and some definition of "acceptable"
- What about the same code for fixed P?
 - identical output for two runs on same number of processes?
 - should be achievable with some care
 - not in specific cases like dynamic task farms
 - possible problems with global sums
 - MPI doesn't force reproducibility, but some implementations can
 - without this, debugging is almost impossible

- Some parallel approaches may be simple
 - but not necessarily optimal for performance
 - casestudy example is very simple due to 1D decomposition
 - but not particularly efficient for large P
 - often need to consider what is the realistic range of P

Some people write incredibly complicated code

- step back and ask: what do I actually want to do?
- is there an existing MPI routine or collective communication?
- should I reconsider my approach if it prohibits me from using existing routines, even if it is not quite so efficient?

Optimisation

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Keep running your code

- on a number of input data sets
- with a range of MPI processes

If scaling is poor

- find out what parallel routines are the bottlenecks
- again, much easier with a separate comms library

If performance is poor

- work on the serial code
- return to parallel issues later on





- Run on a variety of machines
- Keep it simple
- Maintain a serial version
- Don't assume all bugs are parallel bugs
- Find a debugger you like (good luck to you)